



MICRO PHOTON DEVICES

HERMES

Single Photon Camera

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Hermes User Manual Version 1.0.5 - July 2023

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Safety and Regulatory Information


This Safety and Regulatory Information document, together with any other documentation you have received with the Product, will help you in using the Product safely and efficiently. Therefore, follow the instructions provided here, in the User Manual and in any other provided Product documentation. In these safety instructions, the word "Product" refers to all merchandise sold and distributed by Micro Photon Devices Srl, including instruments and all accessories.

Intended use

The Product is intended for use in a laboratory environment. Use the Product only for its designated purpose. Observe the operating conditions and performance limits stated in the data sheet.



Do not operate the Product in a manner not specified in the user documentation. Product misuse can result in a hazard. You can compromise the safety protection built into the Product if the Product is damaged in any way. If the Product is damaged, return it to Micro Photon Devices Srl for repair.

The  symbol on an instrument means caution, risk of danger. The user should refer to the operating instructions located in the user documentation in all cases where the symbol is marked on the instrument.

Safety Instructions

Products from Micro Photon Devices Srl are manufactured according to the highest technical standards. To use the Products safely, follow the instructions provided here and in the Product documentation. Keep the Product documentation nearby and offer it to other users. Use the Product only for its intended use and within its performance limits. Intended use and limits are described in the Product documentation such as the data sheet, manuals and this printed "Safety Instructions".

If you are unsure about the appropriate use, contact Micro Photon Devices customer service at info@micro-photon-devices.com. Using the Product requires qualified or specially trained personnel. These users must have a working knowledge of at least one of the languages in which the user interfaces and the product documentation are available. Never open the case of the Product. Only service personnel of Micro Photon Devices Srl are allowed to repair the Product. If any part of the Product is damaged or broken, stop using the Product.

Observe all terminal ratings. To avoid fire or shock hazard, observe all ratings and markings on the Product. Consult the Product manual for further ratings information before making connections to the Product. Terminal ratings can be either reported on the Product or in User Manual. When, for space reason, it is not

possible to report full ratings in a clear manner directly on the Product, the \triangle symbol is placed next to the relevant terminals, instructing the user to read the relevant Sections of the manual. These sections dealing with terminal ratings are marked with the symbol \triangle . Do not apply a potential to any terminal, including the common terminal, that exceeds the maximum rating of the terminal. Ensure that the connections with information technology equipment, e.g., PCs or other industrial computers, comply with the IEC 60950-1 / EN 60950-1 or IEC 61010-1 / EN 61010-1 standards that apply in each case.

Choosing the operating site

Only use the Product indoors. The Product casing offers no special protection from water and is not protected against any physical contact or objects (IPX0). Water that enters can electrically connect the casing with live parts, which can lead to electric shock, serious personal injury, or death if you touch the casing.

Keep a minimum distance of 10 cm between any fan openings of the Product (if present) and any object in the vicinity and do not place the Product next to heat-generating equipment such as radiators or other instruments or appliances.

Use the Product as specified in Ambient Operating Conditions. It is suitable for pollution degree 2 environments where nonconductive contamination can occur and an overvoltage category of level II. Upon receiving the Product, consider that it may have been stored in different ambient conditions. Allow enough time before plugging in the Product, to reach the Ambient Operating Conditions. Never use the product under conditions in which condensation has formed or can form in or on the product, e.g., if the product has been moved from a cold to a warm environment. Penetration by water increases the risk of electric shock.

Ambient Operating Conditions

- For indoor use only.
- For altitudes up to 2000 m above sea level.
- Temperature range is from 5 °C to 40 °C.
- Maximum relative humidity: 80 %, for temperatures up to 31 °C, decreasing linearly to 50 % relative humidity at 40 °C.
- Main power supply: Voltage fluctuations not to exceed +/- 10 % of the nominal value.
- Additionally, check the specific Product user manual since the ambient operating conditions may be further reduced to guarantee the stated specific Product performance.

Storage Conditions

When not in use, store the Product in a dry place not exposed to direct sun light, with temperature in the range -25° to 65°C , non-condensing.

Connecting to the power

The product is an overvoltage category II product. Connect the Product to a fixed installation used to supply energy-consuming equipment such as household appliances and similar loads. Keep in mind that electrically powered products have risks, such as electric shock, fire, personal injury or even death.

Take the following measures for your safety:

- Use only the provided power supply. It complies with country-specific safety requirements. In case you need a different plug type, contact Micro Photon Devices Srl customer service. Do not try to plug the power supply into the wrong socket type.
- Before switching on the Product, ensure that the voltage and frequency indicated on the Product match the available power source.
- Ensure that you can disconnect the Product from the power source at any time. Pull the power plug to disconnect the Product. The power plug must be easily accessible. If the Product is integrated into a system that does not meet these requirements, provide an easily accessible circuit breaker at the system level.
- Never use the Product if the power cable is damaged. Check the power cables on a regular basis to ensure that they are in proper operating condition.
- Never use the Product if the enclosure is damaged.
- This Product is not equipped with a power switch, therefore for powering it ON simply connect first the provided power supply to the Product and then the power supply to the electrical socket. To power off the module simply disconnect the power supply from the electrical socket.

Maintaining

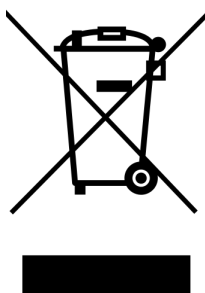
The Product does not need any specific maintenance and does not include any user-serviceable part. To remove dust or dirt follow the instruction in the paragraph Cleaning the Product.

Cleaning the Product

Prior to cleaning the Product, disconnect it completely from the power supply. Use a dry, lint-free cloth to clean the Product. When cleaning, keep in mind that the casing is not waterproof. Do not use liquid cleaning agents.

Disposal

A product that is labeled as follows cannot be disposed of in normal household waste after it has come to the end of its service life. Waste electrical and electronic equipment must not be disposed of with unsorted municipal waste, but must be collected separately, according to your local legislation.



Introduction

HERMES is a single photon counting camera based on a 2-D imaging array of 2048 smart pixels, arranged in 64 rows by 32 columns. Each pixel comprises a single-photon avalanche diode (SPAD) detector, an analogue front-end and a digital processing electronics. This on-chip integrated device provides single-photon sensitivity, high electronic noise immunity, and fast readout speed. The imager can be operated at full resolution with a maximum frame rate of about 100,000 frames per second with negligible blind time (dead-time). Inside each pixel three independent counters are integrated. Each one of them can be independently gated through an external signal; counter 1 can also be gated by an internally generated signal (e.g. for FLIM mode acquisition). Counters 2 and 3, instead, can also count downward, with their direction controlled through an external signal.

HERMES pixels feature high photon-detection efficiency (PDE) in the visible and near-UV spectral region, and low dark-counting rates, even at room temperature. The imager is easily integrated into common optical setups thanks to a Thorlabs® SM1 thread, a C-mount mechanical adapter and a high-speed USB 3.0 computer interface. The camera is shown in Figure 1.

The camera differs from conventional Charge-Coupled Devices (CCD) or CMOS sensors because it performs a “fully digital” acquisition of the light signal. Each pixel effectively counts the number of photons which are detected by the sensor during the acquisition time.

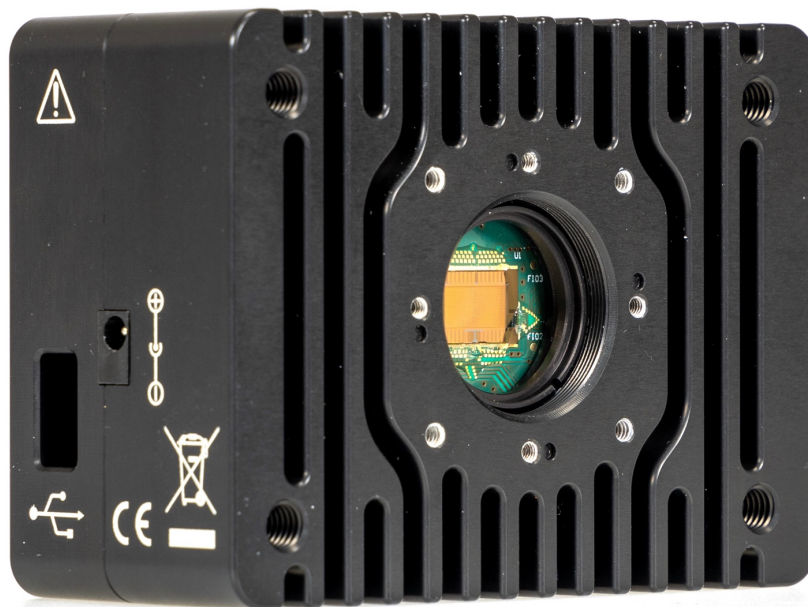


Figure 1. HERMES: Single photon camera.

Single Photon Avalanche Diode

The SPAD is a p–n junction which is reverse-biased well above its breakdown voltage. Under this operating condition, the absorption of a single photon generates an electron-hole pair, which is accelerated by the high electric field across the junction. The energy of the charge carriers is eventually sufficient to trigger a macroscopic avalanche current of few milliamperes through the device. The SPAD biasing electronics, namely the Active Quenching Circuit (AQC), is integrated on the same silicon chip. The AQC senses the avalanche current, quenches it and resets the diode to its initial state. The avalanche is quenched by decreasing the voltage across the SPAD junction below breakdown for an adjustable time (hold-off), that ranges from few tens to few hundreds of nanoseconds. The SPAD bias voltage is then restored to the initial state, and thus the diode is ready to detect the next photon. The total time, which is required to restore the initial state of the SPAD after the detection of a photon, is named dead-time. During the dead-time, no photons can be detected. The AQC provides, additionally, a voltage pulse to an associated counter, which is integrated in each pixel.

The measurement of light signals by a SPAD has several advantages concerning the signal to noise ratio. No analogue measurement of voltage or current is needed since the detector acts like a digital “Geiger-like” counter. It follows that no electronic noise is added by analogue to digital converters or amplifiers while measuring the signal. Additionally, the detector is less sensitive to the electromagnetic interference, or the electrical noise generated by external equipment, differently from charge coupled devices.

The primary noise sources for SPADs are:

- 1) *Dark counts*. This noise source comprises all processes which can start an avalanche across the SPAD junction, but which are not caused by the detection of a photon. The typical source of dark counts is the thermal carrier generation process. Dark counts are the dominant noise source for the SPADs of the HERMES.
- 2) *Afterpulsing*. The detection of a photon can trigger, with a certain probability, an additional detection event within few microseconds. This spurious event is caused by charge carriers, that flew through the junction during the avalanche, remained trapped and are then subsequently released. These carriers are accelerated by the high electric field across the junction and might trigger another avalanche like the photo-generated electron-hole pairs, when released after the dead-time. The afterpulsing probability depends on the detector dead-time and it is usually reduced to about 1-2% at the normal operating conditions. Longer dead-times decrease the afterpulsing probability.

- 3) *Crosstalk*. During the avalanche process, photons are emitted by hot carriers. These can propagate through the silicon and trigger a detection event in SPADs which are placed in proximity. Practically, the Crosstalk probability is very low among the pixels of HERMES (about 10^{-5}), due to the large distance between the SPADs. Its contribution to the total noise is mostly negligible.

Since the read-out noise of CCD or CMOS cameras is normally slightly higher than one electron (per integration time) and since the dark counting rates of the SPAD pixels of HERMES is about one hundred per second, it follows that the optimal operating condition for the camera is at fast or moderate framerates. Particularly, the dark-counts contribution is low with exposure times of about 0.1 s. By reducing even further the integration time, the dark count noise becomes negligible.

Due to the dead time, the SPAD has a linear working range, i.e the number of detection events within a defined time period (T) depends linearly on the illumination intensity, only at low or moderate photon fluxes. At large photon fluxes the number of detected photons deviates from linearity and saturates to a constant value, which is the reciprocal of the dead-time (T_{dead}). As a matter of fact, since the diode is off for a period equal to T_{dead} every time it detects a photon, the maximum count rate happens when the detector oscillates with a period T_{dead} . Supposing N_{imp} the number of impinging photons on a SPAD active area during an integration time T , $N_{counted}$ the photons counted by the detector, and considering the PDE, $N_{counted}$ is equal to N_{imp} reduced by the PDE and multiplied by the ratio of the actual integration time divided by the set integration time T :

$$N_{counted} = N_{imp} * PDE * \frac{T - N_{counted} * T_{dead}}{T} = N_{imp} * PDE * (1 - N_{counted} \frac{T_{dead}}{T})$$

$$N_{counted} = \frac{PDE * N_{imp}}{1 + PDE * N_{imp} * \frac{T_{dead}}{T}} \quad eq. 1$$

By expressing N_{imp} as a function of $N_{counted}$ one obtains also:

$$N_{imp} = \frac{1}{PDE} * \frac{N_{counted}}{1 - N_{counted} * \frac{T_{dead}}{T}} \quad eq. 2$$

The total number of detected events is thus smaller than the total number of photons which cross the p-n junction, because of the saturation effect and the PDE. When $N_{imp} * PDE = \frac{T}{T_{dead}}$, the number of counted events is already reduced of 50%. Since a SPAD is blind for T_{dead} after each triggering, it is also clear that in a time period T , the maximum number of photons that can be counted is:

$$N_{counted,max} = \frac{T}{T_{dead}} \quad eq. 3$$

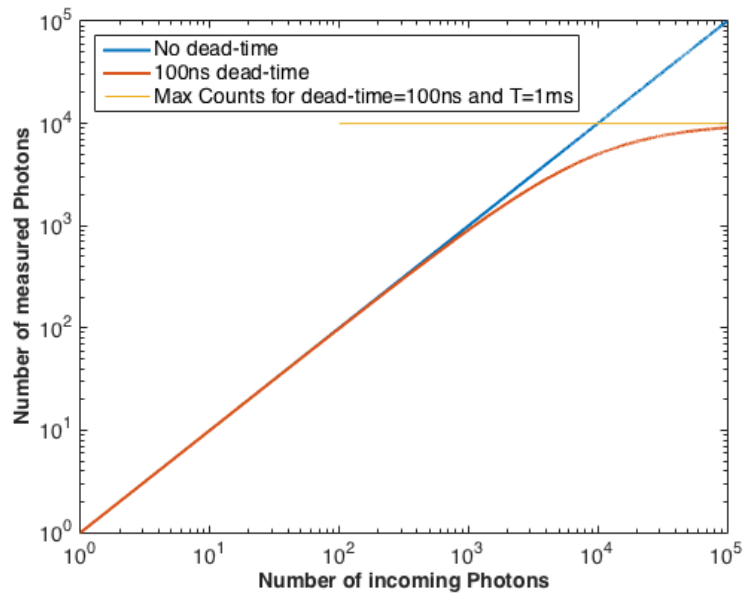


Figure 2. Number of measured photons in an image of 1 ms exposure and dead-time of 100 ns as a function of the number of incoming photons (PDE = 100% for simplicity).

Let's suppose for example an exposure time $T = 1$ ms, a PDE = 50% for simplicity and a dead-time $T_{\text{dead}} = 100$ ns. In this case, the maximum number of photons that can be counted (or more in general the maximum number of SPAD triggerings) is 10'000. In our example also $N_{\text{imp}} * \text{PDE} = \frac{T}{T_{\text{dead}}}$ corresponds to 10'000; this means that when a photon flux of 20'000'000 photons/s hit the detector, during the integration time T , only 20'000 (N_{imp}) photons cross the active area but only 10'000 can be detected due the PDE of 50%, and finally only 5'000 events are, on average, counted (N_{counted}) because of saturation. See, for example, Figure 2 that shows the number of counted photons as a function of the number of the impinging photons for an exposure time $T = 1$ ms, a dead-time of 100 ns and a PDE of 100% for simplicity.

Further readings

1. M. Ghioni, A. Gulinatti, I. Rech, F. Zappa, S. Cova, "Progress in Silicon Single-Photon Avalanche Diodes", *IEEE Journal of Selected Topics in Quantum Electronics*, **2007**, 13, 852-862.
2. D. Bronzi, F. Villa, S. Tisa, A. Tosi, F. Zappa, D. Durini, S. Weyers, W. Brockherde, "100 000 Frames/s 64×32 Single-Photon Detector Array for 2-D Imaging and 3-D Ranging", *IEEE Journal of Selected Topics in Quantum Electronics*, **2014**, vol.20, no.6, pp.354-363.
3. M. Vitali, D. Bronzi, A.J. Krmpot, S.N. Nikolic, F.J. Schmitt, C. Junghans, S. Tisa, T. Friedrich, V. Vukojevic, L. Terenius, F. Zappa, R. Rigler, "A Single-Photon Avalanche Camera for Fluorescence Lifetime Imaging Microscopy and Correlation Spectroscopy", *IEEE Journal of Selected Topics in Quantum Electronics*, **2014**, vol.20, no.6, pp.344-353.

HERMES hardware characteristics

Electrical connections

HERMES has power and USB connections on one side, and a multi-coaxial connector on the other side for various control signals, as shown in Figure 3. HERMES is provided with a cable adapter from the multi-coaxial connector to standard SMA connectors as shown in Figure 4. A description of the input and the outputs can be found in Table 1. The Electrical specifications of the input and outputs are reported in Table 2.



To avoid fire or shock hazard, observe all the ratings below. The ⚠ symbol is placed on the HERMES enclosure next to the relevant terminals. Do not apply a potential to any terminal, including the common terminal, that exceeds the maximum rating of the terminal.

For supplying the HERMES camera use only, the provided power supply.

USB-C connector must only be used to connect the HERMES camera to a PC compliant with the USB standard for data transfer. USB-C connector is not intended for providing power to the camera nor to power any other device.

For using the multi coaxial I/O employ only the provided SMA adapter. The maximum allowed voltage between any pair of SMA shields is 0 V. The maximum allowed voltage between any SMA shields, the USB-C shield and the enclosure is 0 V. The maximum voltage between the signal pin of any SMA and SMA shields is 5 Vrms.



Figure 3. Camera side-views: hardware connections.

Table 1. HERMES Inputs and Outputs description.

USB	High-speed USB 3.0 connector. It is recommended to use short USB cables (< 2 m).
+12V _{DC}	Jack for connecting the provided +12V power supply.
SYNC OUT	Coaxial output which can drive 50 Ohm terminated transmission lines. A 50 Ohm DC load termination is required. Electric pulses of 3.3V LVCMOS are generated at this output for synchronizing the camera with external devices. HERMES can be configured by the user to output the internal 50 MHz <i>reference</i> clock, synchronised with the internal 100MHz <i>master</i> clock, for synchronizing any external instrument (such a laser) with the internal generated gate. The same output can be configured also to generate a signal (pulse) synchronous with the start of each hardware integration frame. The delay between the actual start of the integration frame and the rising edge of this pulse is shown in Figure 5. For more details on gated operation, see the corresponding paragraph in the <i>HERMES Operation</i> section.
TRIG IN	This coaxial input requires a 3.3V pulse (5V tolerated) of minimum duration of 20 ns to synchronize the camera acquisition using a signal from an external device (e.g. a shutter, a laser, etc.). The camera can be programmed to perform the entire measurement after the first pulse is received, or to acquire only a programmable number of frames for each pulse and then pause the acquisition waiting for the following pulse. The frame starts between 20ns and 40ns after the TRIG IN rising edge. Since the TRIG IN signal is asynchronous respect to the internal clock, such delay is of course not-deterministic (unless it is synched with the SYNC OUT signal). The input impedance is 50 Ohm. See Figure 5 for reference.
GATE IN 1 GATE IN 2 GATE IN 3	Active-low inputs with 50 Ohm DC input impedance. Each input controls one of the three in-pixel counters. When GATE IN is '1', the incoming photons are not counted by the measuring electronics. 3.3V LVCMOS signals are accepted but the inputs are 5V tolerant. The minimum duration of a GATE IN pulse is 5 ns. The actual internal gate is delayed by about 15ns.
DIR	Input to select the counting direction of counters 2 and 3. The input has a 50 Ohm DC input impedance; 3.3V LVCMOS signals are accepted but the input is 5V tolerant. A low value means UP counting. DIR timings TBD.

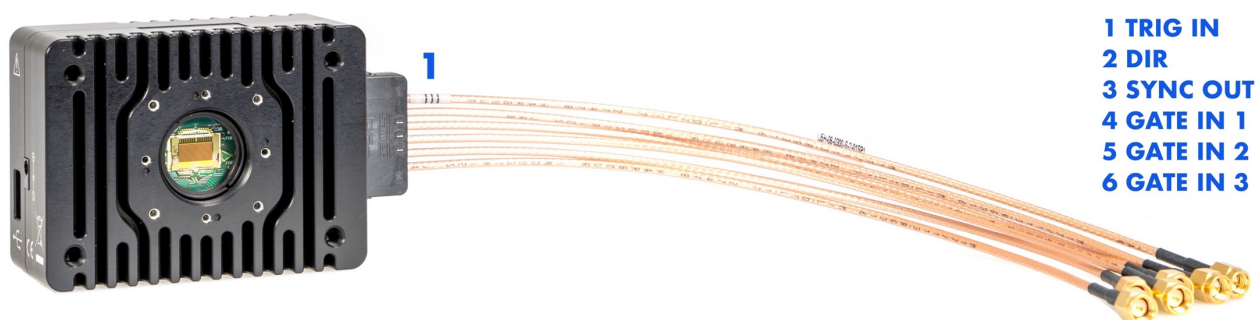
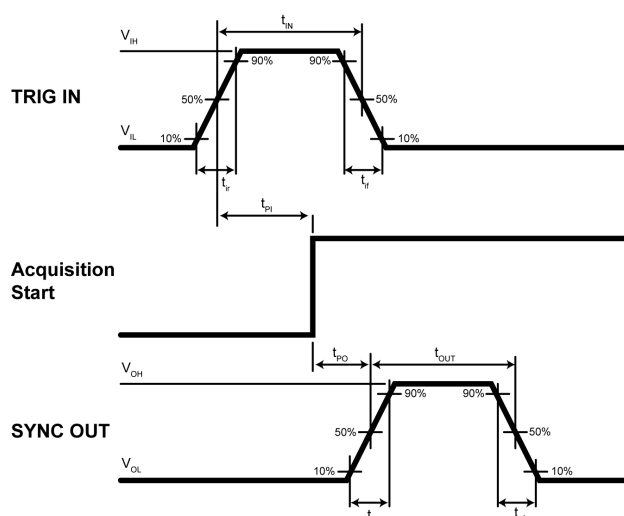
**Figure 4. Camera with the cable adapter and the SMA output description.**

Table 2. Electrical Characteristics of the HERMES measured at room temperature (25°C)

Symbol	Parameter	Signal	Min	Typ.	Max	Unit
V_{IH}	Input logic-high voltage (5V tolerant)	TRIG IN, GATE, DIR	2.4		3.3	V
V_{IL}	Input logic-low voltage	TRIG IN, GATE, DIR	0		0.8	V
V_{OH}	Output logic-high voltage (50Ω load)	SYNC OUT		2.7		V
V_{OL}	Output logic-low voltage (50Ω load)	SYNC OUT		0		V
t_{PI}	Propagation delay from TRIG IN to acquisition start	TRIG IN	20		40	ns
t_{IN}	TRIG IN pulse duration	TRIG IN	40			ns
t_{PO}	Propagation delay from acquisit. start to SYNC OUT	SYNC OUT	5		10	ns
t_{OUT}	SYNC OUT pulse duration (frame sync mode)	SYNC OUT		50		ns
t_{ir}	Input rise time (10%-90%)	TRIG IN, GATE			5	ns
t_{if}	Input fall time (10%-90%)	TRIG IN, GATE			5	ns
t_{or}	Output rise time	SYNC OUT		1		ns
t_{of}	Output fall time	SYNC OUT		1		ns
t_{gate}	GATE pulse duration	GATE	5			ns
t_{gate_delay}	GATE delay	GATE	10	15	20	ns
-	Internal reference clock frequency	SYNC OUT, internal		50		MHz
-	Internal reference clock duty	SYNC OUT, internal		50		%
-	Interframe deadtime	-	30	40	50	ns
	(Measured from SYNC OUT rising edge)					
-	SPAD deadtime	-	50		150	ns
-	Camera Internal memory	-		1024		MiB
-	Number of bits of the Internal Counters	-		9		
-	Hardware Readout Time (1 Counter read)	HRT		10.4		μs
-	Hardware Readout Time (2 Counters read)	HRT		20.8		μs
-	Hardware Readout Time (3 Counters read)	HRT		31.2		μs
-	Hardware Integration Time	HIT	HRT		0.65	ms
-	Frame Exposure Time	-	1		65534	HIT
-	SYNC OUT Frequency FLIM Mode	-		50		MHz

**Figure 5. Timing of TRIG IN and SYNC OUT signals with respect to the actual start of the acquisition.**

Camera mechanical dimensions

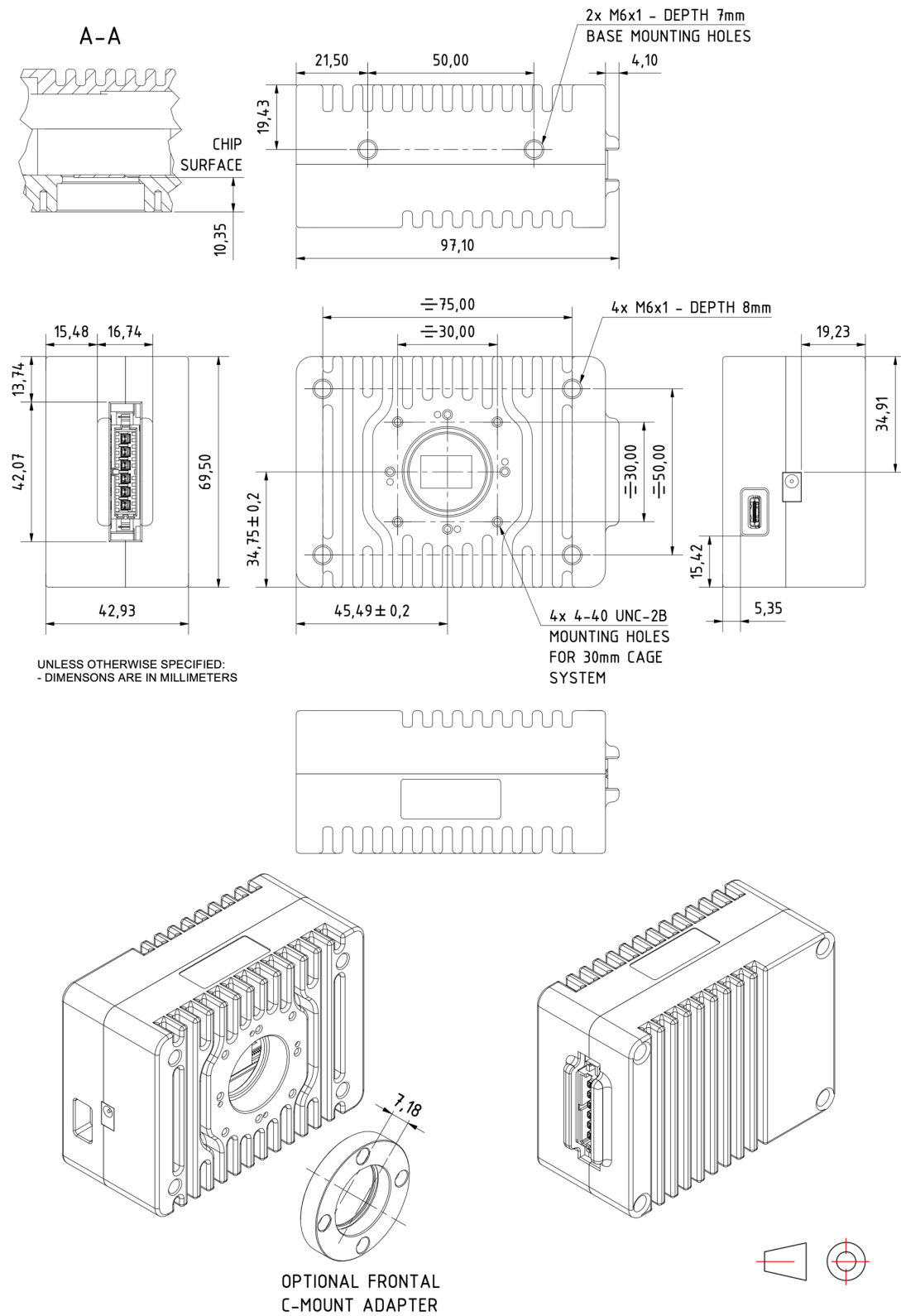


Figure 6. HERMES mechanical dimensions. All dimensions in mm. Camera weight is 720 g.

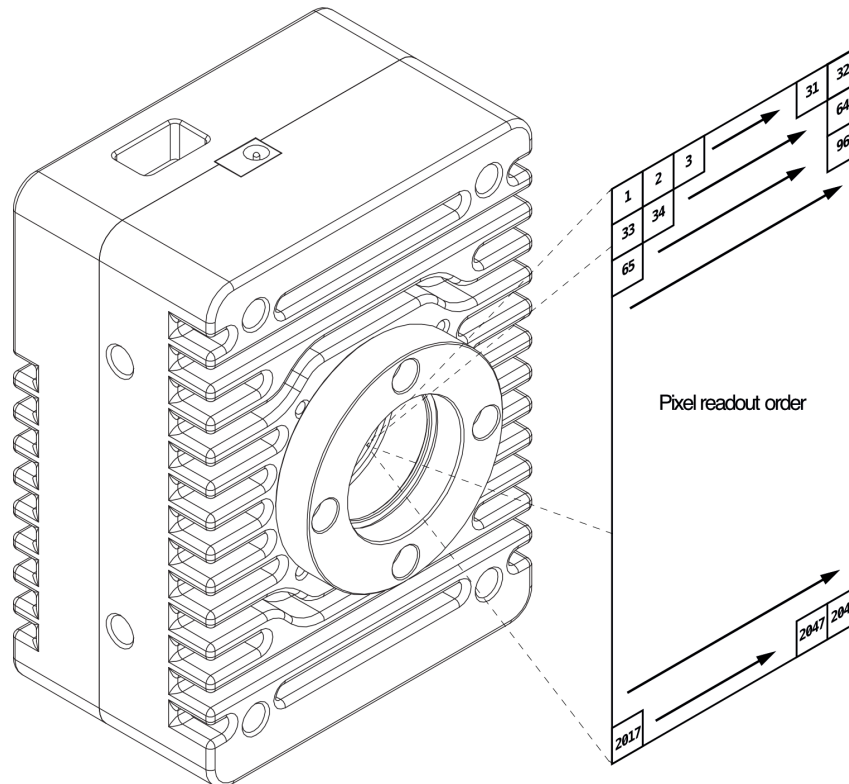


Figure 7. Hermes imager orientation and readout order with reference to the camera mechanical enclosure.

Camera optical properties and Microlens Array characteristics

The Hermes camera is based on an array 64x32 SPAD sensors organised in 64 rows and 32 columns as shown in Figure 7. The SPAD pixels have a round active area of $30\ \mu\text{m}$ diameter and $150\ \mu\text{m}$ pitch (see paragraph on Specifications). Seen from another perspective, the Hermes camera can be thought as based on an imager composed by an array of 64x32 square pixels, each one having the side of $150\ \mu\text{m}$, side by side and no gaps in-between, but where only a portion of the pixel is actually active: a round area of $30\ \mu\text{m}$ diameter in the centre (i.e. the SPAD sensor active area).

Therefore, we can define two different Photon Detection Efficiencies (PDE):

1. A SPAD-PDE as the PDE of the active area of the SPAD sensor
2. A ImagerPDE as the PDE of the square pixel with $150\ \mu\text{m}$ side.

The SPAD-PDE for the Hermes is shown in Figure 8. The ImagerPDE can be calculated multiplying the SPAD-PDE by the imager fill factor, defined as the ratio between the pixel area and the SPAD sensor area. In case of an imager without a microlens array (MLA), the fill factor (also called native fill factor in this case) is a pure geometrical calculation and, for the Hermes, equals to 3.14 %. In case of an imager with a MLA, the fill factor can be calculated by multiplying the native fill factor by the MLA Concentration Factor (CF), defined as the ratio between the collected light with lenses and the collected light without lenses.

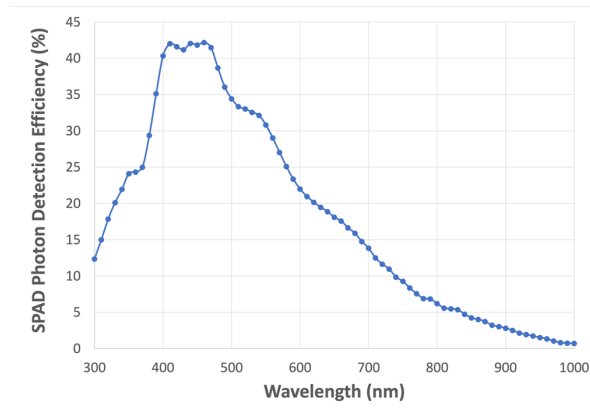


Figure 8. SPAD-PDE, i.e., the PDE of the active area of the SPAD sensor

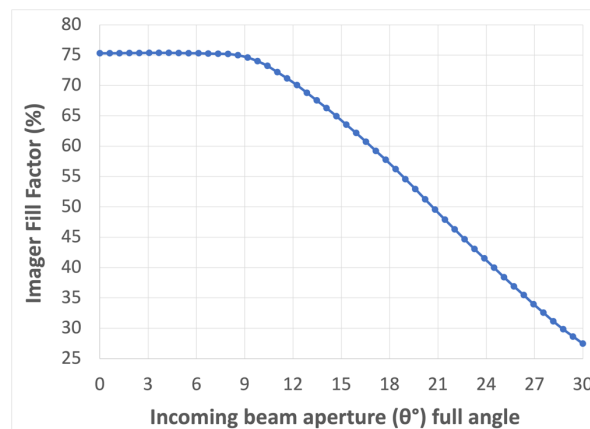


Figure 9. Imager fill factor, defined as the ratio between the pixel area and the SPAD sensor area.

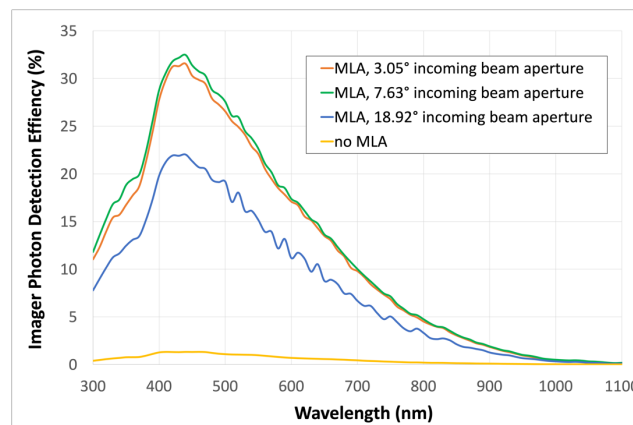


Figure 10. Hermes measured ImagerPDE: without MLA and for three incoming beam apertures when with MLA.

The CF actual value will depend slightly on the incoming beam wavelength and greatly on its aperture. Figure 9 shows the calculated imager fill factor for a Hermes camera having a SPAD array with MLA, as a function of the incoming beam aperture (full angle). Data in Figure 9 has been obtained averaging over three different wavelengths (400 nm, 600 nm and 800 nm). Figure 10 shows measured ImagerPDEs for a Hermes in case no MLA is used and at three incoming beam apertures, when a MLA has been mounted on it. By comparing Figure 8 with Figure 10, it is worth noting the smoothing effect of the MLA on the PDE ringing.

HERMES Operation

HERMES camera features three different modes of operation that can be optimised through the use of several working parameters, all controllable from a computer using either the delivered SDK library or the provided Windows® PC software. The following paragraphs describe in detail all these features.

Standard operation

The camera is operated in its *standard* mode when each pixel is simply used to count photons in a user defined integration time and the counters are not gated (see the next paragraph for details). When HERMES is operated in this mode, three different acquisition modes are possible:

- *Live acquisition*: single images from the camera are acquired and downloaded to the computer. Since in this mode it is the PC that continuously asks for new images, the time between two images can not be precise and strongly depends on how the PC software behaves and on the PC's current work load. This mode should not be used for actual scientific acquisition, but it is instead useful for acquiring a low frame rate "live" movie (i.e. real-time), for instance when aligning the camera in the optical setup or adjusting the acquisition parameters with the current illumination conditions. Considering the practical limitations of the USB connection when transferring small data blocks, typical achievable frame-rates are in the range of 50-100 fps (actual values depend on the performance of both the PC hardware and the software employed). As a consequence, the PC requests of live images should be limited to a maximum of 1 every 10 ms or longer time.
- *Snap*: a sequence of images is acquired and stored into the internal memory of the camera. The dead period between subsequent frames (inter-frame dead-time) is less than 10 ns, and the frames' timing is accurately determined by the internal clock. Once the required number of frames is measured, the electronic interface transfers the data to the computer. The images can then be displayed and saved on the hard-drive. This mode can not be used for live acquisition, since all data will be downloaded to the PC only at the end of the entire snap, which can last few seconds. Instead, this approach allows data acquisitions at the maximum frame-rate possible, since it does not depend on the actual throughput of the USB link or PC save speed. Snap size is limited by the capacity of the internal memory (128 MiB). For more details on how to calculate snap size, see the paragraph on *Camera Configuration*. If you need to acquire more data you should use *Continuous Acquisition* mode, as described below.
- *Continuous Acquisition*: a continuous acquisition of data between a START command and a STOP command from the PC is performed. Once the acquisition is started, the internal memory is used as

a buffer, and data should be continuously read by a PC. In case the internal memory gets full because the PC fails to download the data swiftly enough, data loss occurs, and an error is issued. The maximum achievable frame rate strongly depends on PC performance (specially on the HDD write speed). Thanks to USB 3.0 it is possible to acquire the full array at the maximum speed (about 100kfps). However, to save all generated data at this high throughput it is also crucial that the employed mass-storage unit is very fast (see the paragraph on Camera Configuration for more details on how to calculate actual data rates). SSD storage units are thus recommended. If your PC cannot sustain such a high throughput you will have to reduce the frame rate or to save only half the array. If this is not possible you must resort to the *Snap* mode, at the expense of the experiment duration.

In both *Snap* mode and *Continuous Acquisition* mode it is possible to trigger the actual start of the acquisition with an external signal, or to acquire only a settable number of frames for each trigger pulse.

In all three modes it is possible to output a pulse synchronous with the start of each integration time. It is also possible to internally subtract a background image previously stored into the camera.

Gated operation

Normally, the counters of each pixel of HERMES will just continuously count all the pulses generated by the SPADs. This operating mode is called *free-running* and it is the default operation mode. Anyway, each of the three integrated binary counters, which register the detected number of photons in each pixel, can be *enabled* or *disabled* by a *gate* signal. This operating mode is called *time-gating*.

The *gate* signal actually applied to the counters is the logical OR between two independent digital signals: GATE IN 1/2/3, i.e. each one of the camera coaxial inputs, and *Software gate*, generated internally by HERMES electronics, which can be set by the user through the provided software. Each of the three external GATE IN signals can be periodic or aperiodic and it will be applied asynchronously and directly (through the OR gate) to the SPADs. The *Software Gate* can be either a *Fast Gate* with a period of 20 ns and a resolution of 20 ps, or a *Coarse Gate* with a period equal to the Hardware Integration Time and a resolution of 10 ns. The two modalities are incompatible between them, i.e. it is not possible to apply one gate mode to a counter and the other on another counter. They are also incompatible with FLIM mode and Short Frame feature of Advanced mode, since all these modalities rely on the same hardware signal.

When HERMES is operated in gated mode, the same three acquisition modes of the *standard operation* are possible, this time in conjunction with the use of the three gates.

Fast Software Gate

The *Fast Software Gate* is a periodic digital signal, which is synchronized with the internal *Reference clock* (20 ns period). When a single gate is used on counter 1, the user can set the *Delay*, i.e. the time shift between the rising edge of the *Reference clock* and the high-to-low transition of *Software gate*, and the parameter *Width*, which defines the duration of the “counter-enabled” *Software gate* pulse. Essentially, the *Software gate* generates a periodic gate signal of a given *Width* and *Delay* from the reference clock. Note that the *Width* is the duration of the *Software Gate*’s low state as shown in Figure 11. The *Width* of the *Software Gate*, which is generated by the control electronics, can be varied in the range $0 \div 100\%$ of the reference clock, in steps of 1%. Actually, during a factory calibration, the Gate width has been internally discretized with 1000 points over the full range. In this way, whenever one of the 100 nominal selectable values is requested by the user, HERMES camera is set to the closed possible one, i.e. the one with the smallest possible error. *Note that, however, values below 2 ns could be unreliable.* Particularly the minimum achievable Gate signal is about 1.5ns. The actual set value can be reported to the user by the software. The Delay can be varied in the range $-50\% \div +50\%$ of the Software Gate period, in steps of 0.1%, corresponding to 20 ps.

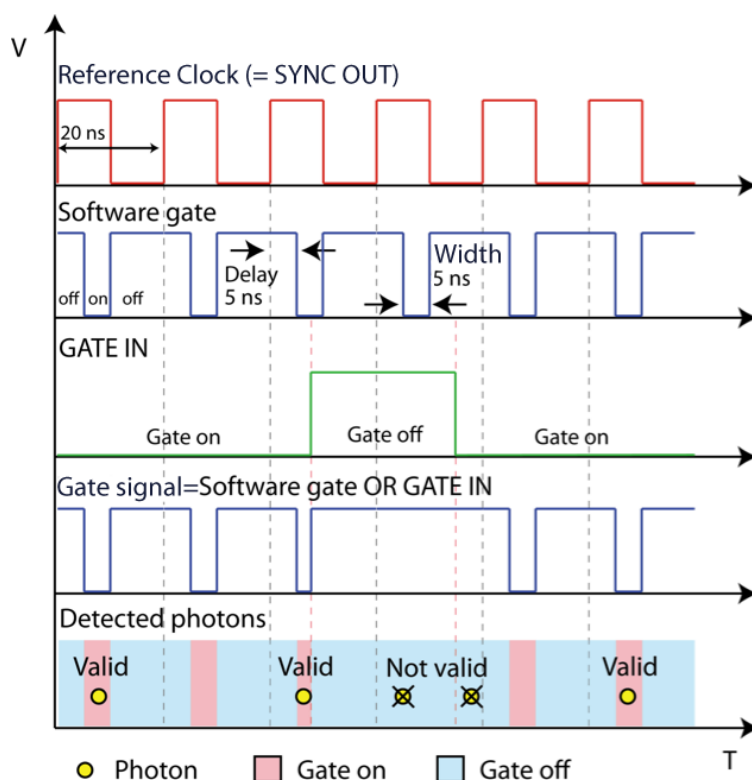


Figure 11. Hardware gating example: Delay = 5 ns and Width = 5ns (both of 25% of the Reference Clock period). The reference clock has been sent to the SYNC OUT output of the camera. Additionally, a GATE IN signal was provided by the user. Only the photons, which are detected when the “Gate signal” is on, are counted. This example is valid for all counters and their associated GATE IN signals.

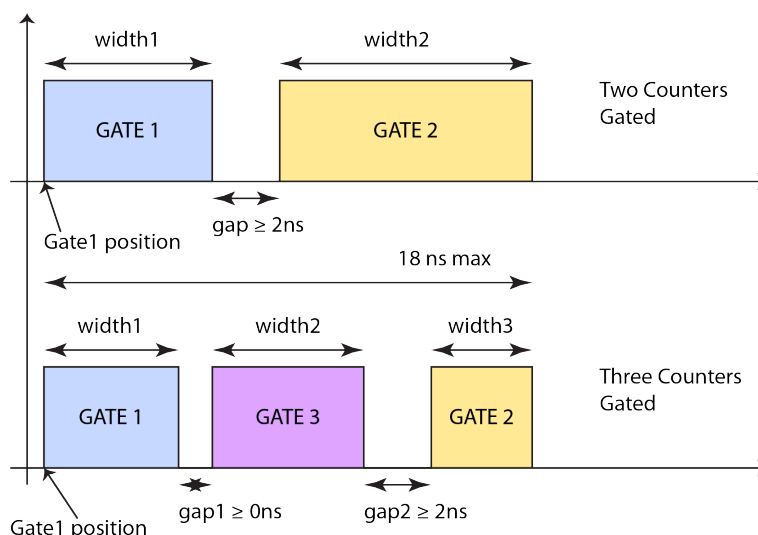


Figure 12. Illustration of the possible gate configurations. Indicated are also the user controllable parameters with their constraint both when only two counters are used and when three counter are selected. Gate sequence is also fixed as must follow the indicated order (color code).

An initial offset may also be present. This offset is on purpose not calibrated, since it will sum up with other setup-dependent offsets (e.g. from different cable lengths). The overall system offset can be evaluated through optical measurements employing a short-pulse laser (i.e. less than 100ps pulse width).

When more than 1 counter is gated using the *Software Gate*, some limitations apply (illustrated graphically in Figure 12). If 2 counters are selected, the user has the option to gate only counter 1 or to use both counters in gated mode. In this latter case, position and width of Gate 1 and width of Gate 2 can be set by user, whereas position of Gate 2 is automatically set at the end of Gate 1 plus a gap selectable by the user, but not smaller than 2ns. Total duration of Gate 1 and Gate 2 plus gap cannot exceed 90% of the gate period of 20ns. If 3 counters are selected, the user has the option to gate only counter 1 or to use all three counters in gated mode. In this latter case, the three gates cannot overlap (even over different periods), and they have to follow in time the order Gate1, Gate 3, Gate2. Position and width of Gate 1, and width of Gate 3 and 2 can be set by user, whereas position of Gate 3 and Gate 2 are automatically set by the function depending on the Gap1 and Gap2 values specified by the user. Gap1 between Gate1 and Gate3 can be as low as 0ns, Gap2 between Gate3 and Gate2 must be higher than 2ns. Total duration of Gate1, Gate3, Gate2 plus Gap1 and Gap2 cannot exceed 90% of the gate period of 20ns.

Coarse Software Gate

The *Coarse Software Gate* is a periodic digital signal with a period equal to the Hardware Integration Time (HIT, see below). For each counter the user can independently enable the gate and define the *Start* and *Stop* positions of the gate-on window inside the HIT period with a resolution of 10 ns. The gate-on window can be as short at 10 ns, and as long as HIT minus 50 ns. *Start* and *Stop* positions are referred to the beginning of the

frame (indicated by the SYNC_OUT signal if enabled and set to HIT Sync mode) plus $40 \text{ ns} \pm 10 \text{ ns}$, e.g. a *Start* value of 100 ns means that the actual opening of the gate will be $140 \pm 10 \text{ ns}$ after the rising edge of SYNC_OUT signal. In other words, as the interframe deadtime is $40 \text{ ns} \pm 10 \text{ ns}$ from the beginning of each frame, when referred to the external SYNC OUT signal, the *Coarse Software Gate* is started only at the end of it.

FLIM Operation

Fluorescence Lifetime IMaging (FLIM) is an imaging technique based on the measurement of the exponential decay rate of the fluorescence from a fluorescent sample, rather than of its emission intensity. The fluorescence lifetime of a molecule is a measurement of the rate of decay of the emission, which is a property of the individual single molecule, and thus it is unaffected by changes in probe concentration or excitation intensity. FLIM can be used for instance as an imaging technique in confocal microscopy and two-photon excitation microscopy.

A typical application of FLIM is the study of Förster Resonance Energy Transfer (FRET), the mechanism of energy transfer between two chromophore molecules with the emission band of one overlapping the absorption band of the other. When this two components are in close proximity, the first one, called donor, initially in its electronic excited state may non-radiatively (without emission of the light) transfer the energy to the second one, called the acceptor. The result is the quenching of the donor fluorescence, thus the decrease of the donor emission lifetime. The efficiency of the energy transfer is inversely proportional to the sixth power of distance between donor and acceptor, making the effect noticeable only at distances shorter than 10 nm. FRET is used to determine the proximity in the nano-meter range between proteins or other elements of interest associated with suitable fluorophores labelled as donors and acceptors. Such measurements are used as a research tool in fields such as biology and chemistry. Different ways of performing FRET measurement exist. The obvious problem with the intensity-based steady-state FRET measurements is that the emission band of the donor extends into the emission band of the acceptor and the absorption band of the acceptor extends into the absorption band of the donor. Furthermore, the concentrations of the donor and acceptor and the fraction of donor molecules linked to an acceptor molecule are variable and unknown. All this makes the intensity-based FRET measurements requiring calibration with the samples containing only donors and acceptors, or measurements in which the second step is the destruction of acceptor by photo-bleaching, obtaining the FRET measurement as the relative increase of donor fluorescence intensity. The FLIM-based FRET measurement has the advantage that the results are obtained from a single lifetime measurement of the donor and are not affected by the changes of the sample concentration, excitation intensity and other factors that limit the intensity-based FRET measurements.

FLIM images are most often obtained by employing the Time Correlated Single Photon Counting (TCSPC) technique and a point detector (such as a PMT), which is then scanned in order to reconstruct the decay histogram for each image pixel. The exponential decay model is fitted to each pixel histogram in order to determine the lifetime. The colour of each image pixel represents the determined lifetime, giving the possibility to obtain images with contrast between materials with different decay rates even if they fluoresce at the same wavelength, or, on the other hand, identify two region of the same material even if they have different intensity. The use of an array of SPADs has major advantages for imaging applications since, as opposed to single pixel systems, it does not require any scan of the sample. A second major advantage of the presented pixel structure concerns the short dead-time, which has a lower limit of about 50 ns, thus allowing the counting of very high photon fluxes.

The embedded short gate capability enables the use of HERMES as a FLIM camera even though the employed SPAD imager chip is only counting the detected photons and it is not time-tagging them. In fact, it is possible to employ the gate in order to implement a time-gated FLIM detection system. In time-gated FLIM the decay of the fluorescence is reconstructed by repetitively counting the number of detected photons in short time windows that are progressively shifted with respect to the excitation laser pulse, as shown in Figure 13. In order to perform this type of measurement, the SYNC_OUT output from HERMES camera has to be connected to the trigger input of a pulsed laser source able to generate optical pulses with width of at most few hundreds of picoseconds. Such laser is then used to excite the fluorescence in the sample under test. The internally generated *Gate* signal activates the counters after the generation of the laser pulse for the time defined by *gate width*. Accordingly, the fluorescence decay kinetics is measured by changing *gate shift* (position) over time. Both *gate shift* and *gate width* have optimal values depending on the lifetime of the excited state of the fluorescent molecules and on the imaging frame-rate.

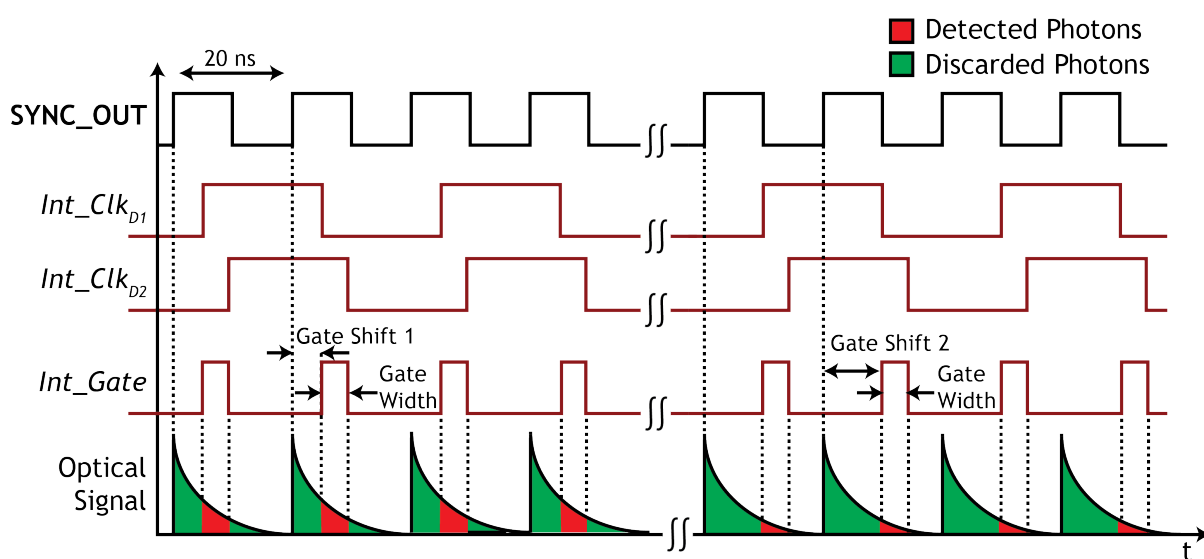


Figure 13. Optical waveform reconstruction using the Gated-FLIM approach with the HERMES camera.

In order to speed-up FLIM acquisitions and increase the frame rate, HERMES includes an automatic FLIM mode in which the internal gate signal is automatically generated with user-defined step-width and shifted of the user-desired number of steps.

Each "FLIM acquisition" is thus composed by a sequence of FLIM elementary (step) frames, one for each desired gate position (step), each one consisting of an acquisition with the same exposure parameters of a standard acquisition. FLIM mode acquisitions are possible in Snap mode and Continuous Acquisition mode whereas a real Live mode is not available, since each FLIM acquisition is composed by several elementary frames. However, the HermesView software (see below) offers a seamlessly equivalent Live mode which is internally implemented performing repetitive Snap acquisitions.

Due to the time required for internal gate shifting (which is also dependent on the shift parameters), the time required for a full FLIM acquisition is not simply the sum of the integration time of each step and it is, instead, conveniently calculated by the camera software and reported to the user. A reference clock inside the camera guarantees that every FLIM acquisition starts only after this time is elapsed, thus ensuring the isochronicity of FLIM acquisitions, and allowing the recording of "FLIM movies".

Exactly as for the *gated operation*, the gate signal is generated synchronized with the internal 50MHz *reference clock*. Its *width* can be varied in the range $0 \div 100\%$ of the reference clock period (20 ns), in steps of 1%, while the *gate shift* can be varied in the range $-50\% \div +50\%$ of the same period, in steps of 0.1%, corresponding to 20 ps. Of course, to make the Gated-FLIM work, the external laser must be synchronised with the gate and thus, in case of FLIM, the SYNC OUT outputs the internal reference clock. Finally, as shown in Figure 13, since the reference clock period is 20ns, the nominal maximum "observation" time window is also 20ns.

The actual width and phase of the gate signal obtained for a given set of parameters may change among different HERMES units, due to fabrication tolerances of the FPGA. That's why the gate width is calibrated by MPD before delivering the camera.

The initial position of the gate in a FLIM sequence is also internally controlled and has an accuracy better than ± 20 ps plus a constant offset (see also paragraph on *Gated Operation*). This *shift-offset* is not calibrated since in case of a FLIM experimental set-up what is important to measure is the full offset of the gate signal with respect to the laser pulse. This offset is not only determined by the internal *shift-offset* due to the camera, but also (and probably largely) by the delays introduced by the used external interconnection cables and the laser itself. A calibration of the actual gate shift with respect to the laser excitation is therefore necessary *after* the camera is mounted into the measurement setup. This can be easily done by directly shining the laser onto the array, without interposing any fluorescent sample or filter, and performing a full measurement over the entire 20 ns shift range. By inspecting the measurement and finding the laser peak, it

is possible to evaluate the shift between the actual laser pulse and the internal reference clock. Actually it is not even important to measure it. What needs to be done is simply the adjustment of the cables' length from the SYNC_OUT of the camera to the TRIG_IN of the laser in order to place the laser pulse at the beginning of the FLIM observation time window. In this way the fluorescence decay will be centred inside the 20 ns FLIM window. This would also prevent any folding of the fluorescence signal and the associated measurement distortion. Such calibration could be useful also to zero any skew among pixels but, in many applications, like the FLIM, it is usually not needed; should it be, the HERMES user can contact MPD at the following email address for more details: imaging@micro-photon-devices.com

FLIM data acquired can be either saved on a multipage TIFF with embedded acquisition metadata according to the OME-TIFF format or in the proprietary HRMF format. For both formats, image data is composed by a set of images following a "FLIM first, time second scheme", i.e. with the following frame sequence: 1st gate shift of 1st FLIM measurement, 2nd gate shift of 1st FLIM measurement, ..., nth gate shift of 1st FLIM measurement, 1st gate shift of 2nd FLIM measurement, 2nd gate shift of 2nd FLIM measurement, ..., nth gate shift of 2nd FLIM measurement, etc.

OME-TIFF file could be opened with any image reader compatible with TIFF file, since metadata are saved into the Image Description tag in XML format. In order to decode OME-TIFF metadata, it is possible to use free OME-TIFF readers, such as OMERO or the Bio-Formats plugin for ImageJ. For more details see the OME-TIFF web site: <http://www.openmicroscopy.org/site/support/ome-model/ome-tiff/>. OME-TIFF metadata include the ModuloAlongT tag, which allows the processing of FLIM data with dedicated FLIM softwares such as FLIMfit (see <http://www.openmicroscopy.org/site/products/partner/flimfit>). A tutorial on basic usage of FLIMfit is available at <http://help.openmicroscopy.org/flimfit.html>. In order to import OME-TIFF file generated by HERMES camera, simply select "Load FLIM data..." from File menu. For further support on FLIMfit please directly contact its developer.

HRMF file are binary files composed by a header with acquisition metadata followed by raw image data, containing the 8/16 bit pixel values in row-major order. HRMF file can be read using the provided ImageJ/Fiji plugin. In addition, since the format is fully documented in HERMES-SDK documentation, users can directly read data from their own code.

Further Readings

1. Joseph R. Lakowicz. Principles of Fluorescence Spectroscopy 3rd edition. Springer (2006).
2. J. Pawley, Handbook of Biological Confocal Microscopy, 3rd Edition. New York: Plenum Press, 2006.
3. T. W. J. Gadella, Ed., FRET and FLIM Techniques, Volume 33. Amsterdam: Elsevier Science, 2008.
4. S. P. Chan et al., "Optimized gating scheme for rapid lifetime determinations of single-exponential luminescence lifetimes." *Anal Chem*, vol. 73, no. 18, pp. 4486–4490, 2001.
5. D. D.-U. Li et al., "Time- domain fluorescence lifetime imaging techniques suitable for solid-state imaging sensor arrays." *Sensors*, vol. 12, no. 5, pp. 5650–5669, 2012.

Acquisition parameters

Integration time

Each pixel of HERMES camera integrates three 9-bit binary counters (two of them with up-down capability), which measure the number of photons detected during a specified *Hardware Integration Time (HIT)*. The *HIT* is thus the time during which the impinging photons are counted without resetting the integrated counters, i.e. the time from when these counters are cleared and started to the time when they are latched and read. It can range from the *Hardware Readout Time (HRT)* of the array to about 0.65 ms. The *Hardware Readout Time* of the array is proportional to the number of counters ($N_{counters}$) in use and it always corresponds to the inverse of the frame-rate. In other words the HRT is the minimum time needed to read the counters in use for all the pixels. HRT value is given by:

$$HardwareReadoutTime = N_{counters} * (5 \text{ ns} * N_{pixel} + 160 \text{ ns})$$

In case of use of a single counter per pixel, this time is equal to the time needed to read the 2048 pixels and is 10.40 μs ; for 2 counters it is equal to 20.80 μs and for 3 counters it is equal to 31.20 μs . It must be also noted that even when saving only half the array, to reduce the mass storage bandwidth requirement, the readout will be carried out for the entire imager and so the *Hardware Readout Time* will not be reduced.

It is also possible to increase the total integration time by internally (inside the camera's internal FPGA) accumulating several *Hardware Integration Time*, in order to obtain the so-called *Frame Exposure Time*. This is a viable solution since HERMES has no readout noise, thus there is no penalty in repeating the readout, apart for a negligible dead-time (or inter-frame dead-time) of less than 10 ns between adjacent *Hardware Integration Time*. The number of *Hardware Integration Times* that are accumulated to obtain a *Frame Exposure Time* can range from 1 to 65534. A beneficial side effect of accumulating several *Hardware Integration Times* instead of using a longer *Hardware Integration Time* is that the equivalent dynamics of the internal counter is increased. In fact, since each *Hardware Integration Time* can accommodate up to 511 photon detections, 2 *Hardware Integration Time* can hold 1022 detections, 10 *Hardware Integration Time* can hold 5110 and so on.

Finally, it is possible to employ the internal detector gating capability of Counter 1 to achieve an *Equivalent Hardware Integration Time* smaller than the *Hardware Readout Time*. This is possible by gating-off the detector during a portion of *Hardware Integration Time*. *Equivalent Hardware Integration Time* can be as short as 10 ns. Please note however, that using an *Equivalent Hardware Integration Time* shorter than the *Hardware Readout Time* results in a corresponding increase in the inter-frame dead-time, by an amount equal to the difference between the *Hardware Readout Time* and the chosen *Equivalent Hardware*

Integration Time. Since in this particular working mode the gate is controlled directly by the camera, it is not recommended to apply any external gate signal or to change the internal gate settings, either with the PC software or with the standard gate-control procedures provided in the SDK. Particularly the new gate settings will overwrite the already applied ones thus interfering with the *Equivalent Hardware Integration Time* generation process.

To configure these three parameters, HERMES can be set into two different modes. In *normal mode* the camera settings are constrained so that the *Hardware Integration Time* is equal to the *Hardware Readout Time*, to avoid or at least reduce to a minimum the probability of the occurrence of an overflow of the integrated counters. In fact, the internal 9-bit binary counters can overflow at long *Hardware Integration Times* and thus induce artefacts in the detected image.

As already shown, the maximum number of photons N_{\max} that can be counted per second, given a dead time of T_{dead} , is:

$$N_{\max} = \frac{1}{T_{\text{dead}}} (\text{counts/second})$$

thus the maximum number of photons that can be counted during a *Hardware Integration Time* equal to T is:

$$N_{\max-HIT} = \frac{1}{T_{\text{dead}}} T$$

For instance, when using a single counter, T is equal to $10.40 \mu\text{s}$ and with the minimum T_{dead} of 50 ns , the maximum counted photons is:

$$N_{\max-HIT} = \frac{T}{T_{\text{dead}}} = \frac{10.40 \mu\text{s}}{50 \text{ ns}} \cong 208 < 511$$

thus, any overflow is avoided since 511 is the maximum number that can be counted by a 9-bit counter before overflowing. Instead, when using all the three counters, T is equal to $31.20 \mu\text{s}$ and with the minimum T_{dead} of 50 ns , the maximum number of photons that can be counted is:

$$N_{\max-HIT} = \frac{T}{T_{\text{dead}}} = \frac{31.20 \mu\text{s}}{50 \text{ ns}} \cong 624 > 511$$

and the overflow may occur with very strong light.

Therefore, to minimise the probability of incurring in overflows, or even to completely avoid them in some cases, a clever strategy is to obtain long *Frame Exposure Times* by accumulating many *Hardware Integration Times*, each equal to the *Hardware Readout Time*, directly in HERMES. Due to the short inter-frame dead-time smaller than 50 ns , this operating mode induces only negligible signal losses and does not increase the noise (since read-out noise is not present in HERMES Camera).

In *advanced mode*, both *Hardware Integration Time* and *Frame Exposure Time* are user adjustable, thus particular care must be taken by the user to avoid artefacts due to the overflow of the integrated 9-bit counters, which is no more avoided or minimized. In addition, also the ability to achieve shorter *Equivalent Hardware Integration Time* on Counter 1, by using the internal gate generation, is enabled. Internal gate is automatically enabled when the user selects a *Hardware Integration Time* shorter than the *Hardware Readout Time*. It is then up to the user the calculus of the actual inter-frame dead-time; for this purpose, since the *Hardware Readout Time* is equal to the inverse of the framerate in *Snap* or *Continuous Acquisition* modes, it could be useful to have a look at the actual framerate by enabling and checking the Sync Out output. Please note that this modality is incompatible with any other use of the gate signal (i.e., internal gate, external gate or FLIM mode). Figure 14 summarizes the relationship between Hardware Integration Time, Readout Time, Frame Exposure Time in the two working modes.

Dead-time time and dead-time correction

SPAD dead-time can be selected between a minimum value of 50 ns and a maximum value which depends on the specific camera but is never lower than 130 ns. There are about 60 discrete values that can be assumed over the full range, thus whenever a value is input by the user, HERMES camera is set to the closest possible value, according to factory calibration. The actual value can be reported to the user by the software.

The dead-time strongly affects the image quality. It limits the after-pulses generated in each single pixel when set at high values, e.g. 150 ns, but it introduces a limitation on the total number of photons per second that each pixel can detect. This induces a non-linearity when bright spots are observed (see the introductory section for further details).

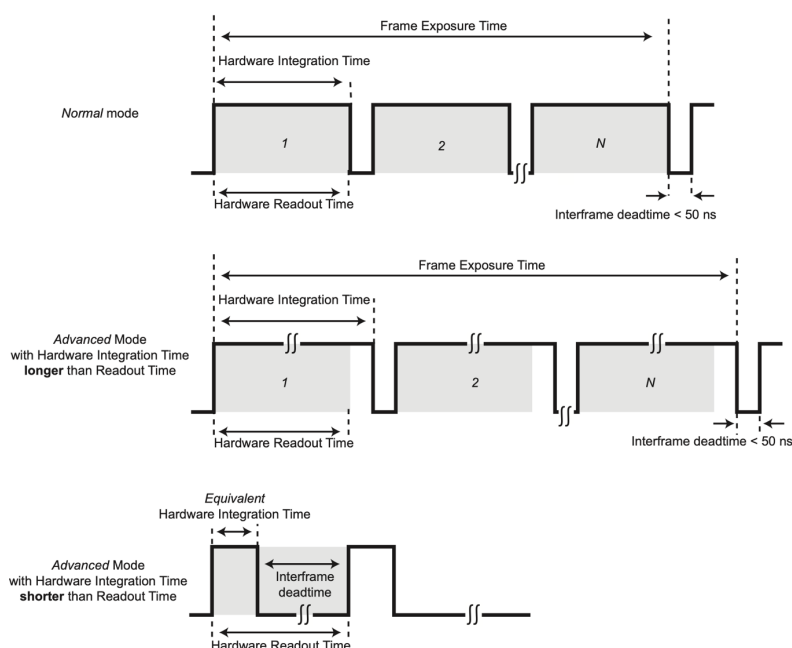


Figure 14. Integration times and working modes.

It is possible to improve the quality of the image by correcting for the non-linearity introduced by the dead-time (see section “Single-Photon Avalanche Diode”). In fact, a simple operation as background subtraction might perform incorrectly when large numbers of photons per second are detected by the pixels. This occurs because, for example, a cumulated flux of 10’000 photons (5’000 signal photons + 5’000 optical background photons) might suffer a larger non-linearity in the detection than the acquisition of only 5’000 optical background photons, as predicted by Eq. 1 and shown in Figure 2. For sake of clarity let’s consider, as before, 5’000 photons per integration window T both for the background and for the signal. Let’s also assume $T = 1$ ms, a dead-time of 100 ns and a PDE = 100% for simplicity. In this situation it follows that only 3’333 photons are counted when acquiring the 5’000 background (BG) photons and only 5’000 are counted when acquiring the cumulated 10’000 photons of signal and background (SG+BG), see Eq.1 for reference. It is thus clear that subtracting the measured 3’333 BG photons from the 5’000 SG+BG photons is totally incorrect and results in the over-subtraction of the background which should have been 2’500 and not 3’333. In any case, the correct way of proceeding is to correct, by means of Eq. 2, for the dead-time effect the actual measured number of photons and obtain the real number of impinging photons (10’000 and 5’000) for both images and only AFTER perform the subtraction.

By enabling the embedded dead-time correction, the effect of the non-linearity is mostly removed and a better and faster processing of the data becomes possible. Figure 15 shows the improvement of the image quality of two “white” frames with automatic background subtraction enabled. The reference image shows a noisier pattern compared to the dead-time corrected one. This is due to an “over-subtraction” of the background, caused by dead-time induced non-linearity.

The effect is even more visible in the intensity histogram on the right of Figure 15. The histogram of the reference image deviates from an expected Gauss-like profile and shows a remarked shoulder for lower number of photons (green curve). Conversely, the corrected image is closer to the ideal Gauss distribution (blue curve).

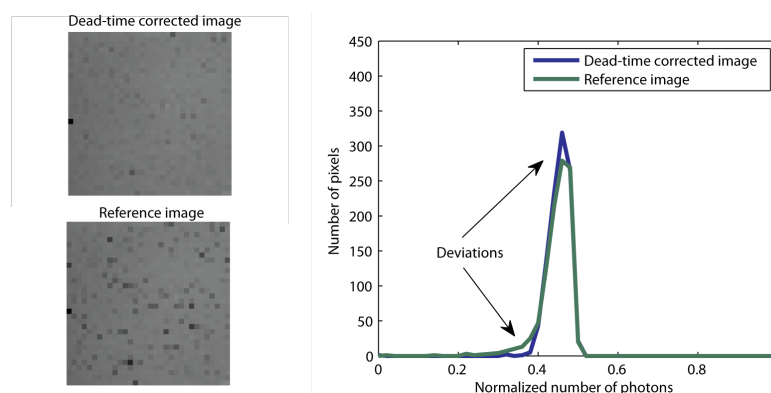


Figure 15. Improvement of the image quality by using the dead-time correction algorithm. The intensity histograms of the two images are plot on the right.

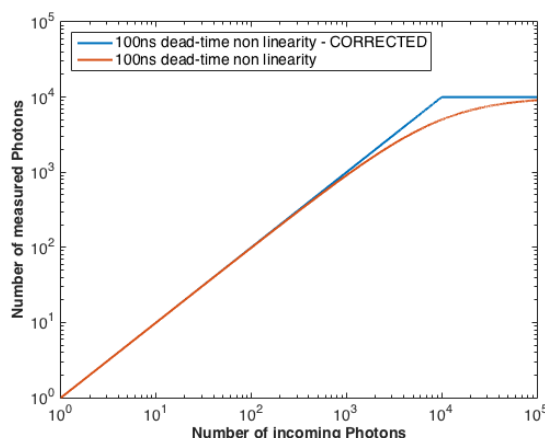


Figure 16. Effect of the dead-time corrector in an image of 1 ms exposure and dead-time of 500 ns as a function of the number of incoming photons.

It must be observed that the dead-time correction is only effective under a moderate illumination of the sensor. For this reason we have decided that the SW implemented dead-time correction, does compensate the non-linearity shown in Figure 2 but it does not in any case expand the counting range beyond the natural limit imposed by the hold-off time, as shown in Figure 16. Therefore, when a strong illumination is applied, the corrected values will in any case saturate to the expected saturation level given by the current hold-off time.

Background subtraction

HERMES can perform **in-camera background subtraction**. For this purpose, the user must have previously acquired a dark image (i.e. with the shutter close) *with the same parameters of the actual acquisition* (i.e. the same integration time, hold-off and gate), and then has to enable the background subtraction.

Subarray acquisition

It is possible to set the camera in a special *SubArray* mode that allows the reduction of the minimum integration time (which is imposed by the minimum readout time) by reducing the number of pixels acquired. When set to *SubArray* mode, the camera will only acquire the programmed number of pixels, starting from the top-left corner and moving by lines of 32 pixels toward the center of the detector. The Hardware Readout Time will be $N_{pixels} * 10\text{ ns} + 160\text{ ns}$. Some limitations apply:

- in *Live* mode it is possible to acquire only 1, 2, 4, 8 full rows. If Live mode is started when the camera is set for a different number of pixels, an error will be returned;
- using the SDK, in *Snap* and *Continuous* mode any number of pixels ranging from 1 to 256 in the upper semiarray can be acquired (in any case starting from the corner and then reading by lines, i.e. if 67 pixel are required 2 lines of 32 pixels + 3 pixels from the third line will be acquired), PROVIDED that

the total data acquired is an integer multiple of 1024 bytes. For the example above and assuming the camera is set to 8bit/pixel, this means that 1024 frames (or multiples) must be acquired, so that the total data to acquired (67 * 1024 bytes) is an integer multiple of 1024. Acquisitions with a smaller number of frames are not possible. If an acquisition is triggered with invalid values of the parameters, an error will be returned;

- using HermesView, in *Snap* and *Continuous* mode the same limitation of Live mode apply, so it is possible to acquire only 1, 2, 4, 8 full rows;
- the *SubArray* acquisition is only available when using 1 counter and it is not compatible with the Coarse Gate Mode.

Additional information

Calculation of the Snap size and the Continuous Acquisition Data rate

Integration Time and *Half-Array Saving Mode*, directly influences the data size of a single *Snap* mode acquisition and the data rate in *Continuous Acquisition* mode.

Snap mode data size, in bytes, is given by:

$$Snap_Size = N_{pixel_Saved} * N_{frames} * \frac{BPP}{8}$$

where N_{frames} is the number of frames in the Snap and bit-per-pixel (BPP) is 8 if there is no internal accumulation of several Hardware Integration Times and both dead-time correction and background subtraction are off, 16 otherwise. N_{pixel_Saved} is the number of saved pixel and currently can be 2048 (full array) or 1024 (half array).

Continuous Acquisition mode data rate, in bytes-per-second, is given by:

$$CA_DataRate = N_{pixel_Saved} * \frac{BPP}{8} * FrameRate$$

$$FrameRate = \frac{1}{Hardware_Readout_Time * N_{sums}}$$

being N_{sums} the number of internal accumulations.

Camera auto-protection

HERMES has a protection mechanism that shuts down the SPAD high voltage when too much current is flowing through the array, for example when really high photon fluxes are impinging on the camera. Solution: Reduce the amount of light that falls on the sensor, disconnect and reconnect the camera to the host PC and restart the software.

HERMES GUI – HermesView (Windows only)

The camera is provided with an acquisition and control software, which is running on Microsoft Windows operating systems: *HermesView*. This software provides a direct access to all the camera functions and it is a basic tool to display images. It is recommended to use the Software Development Kit for a more flexible camera control. Due to the start-up time needed by the internal firmware to be fully working, the *HermesView* should be started at least 15 seconds after having powered HERMES. Failing to do so will generate an error by the software. Simply close and restart the software.

Installation

Double-click the desired installer (32-bit or 64-bit) and follow the guided installation procedure. Please note that device driver from OpalKelly, provided on the HERMES USB-Key, must be installed before connecting the camera to the PC.

Software Interface

The *HermesView* interface is composed a main window divided in several sections as showed in Figure 17, and a separate window for each active counter (see Figure 18). An additional window will also pop-up when FLIM mode is enabled (see Figure 19) or when Time Plot is enabled (see Figure 20). Settings can be saved and recalled using the *Save Settings* and *Recall Settings* buttons in the upper left section of the main window.

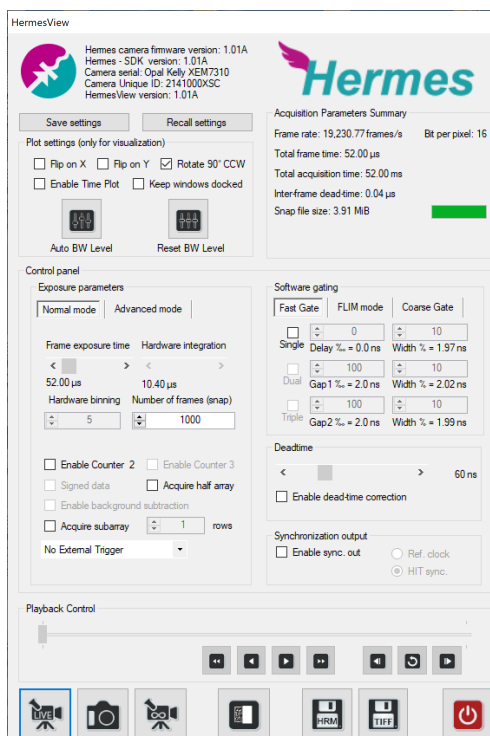


Figure 17. Screenshot of the main window of the graphical user interface.

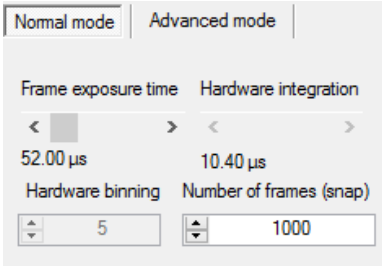
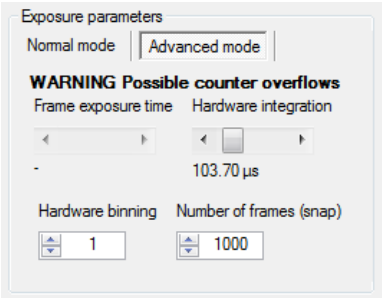
Main window: Control Panel

This panel allows setting all the camera hardware parameters.

In the Exposure Parameters subsection it is possible to set the image integration parameters (*exposure time*, *number of frames* for Snap mode and *hardware binning*). Either *normal* or *advanced* modes are available. There are four numeric fields (see Table 3 for an example of settings), which can be either editable or automatically adjusted by the software depending of the selected mode, namely:

- ✓ *Frame exposure time (Normal only)*: integration time for each frame required by the user. The possible values range between 10.40 μ s and 2.40 ms. This value does not correspond to the *Hardware Integration Time* of the sensor. Longer exposure times are obtained by binning a variable number of frames.
- ✓ *Hardware Integration time*: physical integration time of HERMES sensor. This value is fixed to the *Hardware Readout Time* in *normal mode*. In *advanced mode*, it can range from 10 ns to 655.25 μ s.
- ✓ *Hardware binning*: number of frames of duration equal to *Hardware Integration Time* that are summed-up before being stored in the computer memory. In *Advanced* mode this field can be changed by the user, in *Normal* mode it is adjusted by the software depending on the chosen *Frame Exposure Time*
- ✓ *Number of frames*: number of frames that are acquired during a *Snap* event. This number ranges from 1 to 65534 for 16 bit images and to 131070 for 8 bit images.

Table 3. Possible configurations of the Exposure Parameters subsection (Normal and Advanced mode)

<div><p>Normal Acquisition Control Box</p></div>	<p>The duration of a frame is obtained by binning a sequence of frames of shorter exposure times. In this example, a 52.00 μs <i>Frame exposure</i> is obtained by summing 5 frames of 10.40 μs. This acquisition is then repeated 1000 times and the data are transferred to the host computer. Practically, 5000 frames of 10.40 μs are acquired and binned by a factor of 5. This acquisition mode does not degrade the signal-to-noise ratio of the images because no read-out noise is present.</p>
<div><p>Advanced Acquisition Control Box</p></div>	<p>The user has a full control on the frame acquisition. In the example, each frame has an effective duration of 103.7 μs and no binning of the frames is performed (<i>Hardware binning</i> = 1). The acquisition is then repeated 1000 times and the data are transferred to the host computer. Frame exposures down to 10 ns can be obtained.</p> <p>WARNING the integrated counters can overflow at long exposure times.</p>

In this subsection there is also a set of checkboxes to further customizing the acquisition. The full list and their explanation can be found in Table 4.

Table 4. List of checkboxes in the Exposure Parameter subsection and their explanation

<i>Acquire half array</i>	Only the central 32x32 portion of the array is acquired. Useful to reduce required bandwidth.
<i>Enable Counter 2</i> <i>Enable Counter 3</i>	Enable the extra in-pixel counters. When a counter is enabled, a new Counter window pop-ups, when a counter is disabled the corresponding window is closed.
<i>Signed data</i>	When at least Counter 2 is enabled, this checkbox indicates to the software if the data from Counter 2 and 3 has to be considered signed or not. Useful when these counters are employed in up/down mode. Note that, if negative values are expected, this checkbox MUST be checked, otherwise data will be incorrect.
<i>External Trigger</i> <i>(Frames per Trigger)</i>	Specify the type of external trigger. <i>No Trigger</i> means that the camera will start acquisition as soon as the command is received. <i>Single Trigger</i> means that the camera will wait for a pulse on the SYNC_IN input before starting the complete acquisition. <i>Multiple Trigger</i> means that, when a pulse on the SYNC_IN input is received, the camera will acquire only the number of frames defined in the field <i>Frames per Trigger</i> and then wait for the next pulse.
<i>Enable background subtraction</i>	The acquired dark frame is subtracted by the output image. A dark frame acquisition must have been previously performed (see the Control Buttons paragraph).
<i>Force 8bit mode</i>	Available only in <i>Advanced</i> mode. Data are truncated to 8bit. Useful to reduce required bandwidth.
<i>Acquire SubArray</i>	Enable subarray acquisition of the number of rows specified. Note that some limitations apply.

In the Software Gating subsection it is possible to configure the internal gate generation. Three gated operation modes are possible, *Short Gate mode*, *FLIM mode* and *Coarse Gate*.

In *Short Gate mode* a periodic signal at 50 MHz is continuously applied to counters, as explained in Table 5. For details on multi-gate mode see the paragraph on *Gated Mode*

Table 5. Short Gating section configuration explained.

Single	Enable/Disable the internal gating of counter 1
Dual	Enable/Disable the internal gating of counter 1 and counter 2
Triple	Enable/Disable the internal gating of counter 1, counter 2 and counter 3
Delay	Change the delay of the gate signal of counter 1 respect to the internal reference clock. The delay value is expressed in thousands of the reference clock period (20 ns). E.g. Delay = +100‰ → +2 ns delay
Width1	Duration of the gate-on signal for counter 1. This is expressed as a percentage of the internal reference clock period (20 ns). E.g. Width = 20% → 4 ns width.
Width2	Duration of the gate-on signal for counter 2 in dual and triple gate mode. This is expressed as a percentage of the internal reference clock period (20 ns). E.g. Width = 20% → 4 ns width.
Width3	Duration of the gate-on signal for counter 3 in triple gate mode. This is expressed as a percentage of the internal reference clock period (20 ns). E.g. Width = 20% → 4 ns width.
Gap1	Gap between the gate of the counter 1 and counter 2 in dual gate mode. Gap between the gate of counter 1 and counter 3 in triple gate mode. This is expressed in thousands of the reference clock period (20 ns). E.g. Gap = +100‰ → +2 ns
Gap2	Gap between the gate of counter 3 and counter 2 in triple gate mode. This is expressed in thousands of the reference clock period (20 ns). E.g. Gap = +100‰ → +2 ns

In *FLIM mode* the internal gate is automatically controlled in order to perform a gated FLIM acquisition with parameters explained in Table 6. See paragraph on FLIM operation for further details.

Table 6. FLIM mode section configuration explained.

Enable FLIM mode	Enable/Disable FLIM mode. When FLIM mode is enabled an additional FLIM window pop-ups (see paragraph below).
Gate Width	Duration of the gate-on signal. This is expressed as a percentage of the internal reference clock period (20 ns). E.g. Width = 20% → 4 ns width.
FLIM steps	Number of steps to be performed for each FLIM acquisition.
FLIM shift per step	Gate shift for each FLIM steps in thousandths of reference period. E.g. Step = 50‰ → 1 ns step
FLIM Start position	Start position of the of the first FLIM step with respect to the internal reference clock. This value is expressed in thousands of the reference clock period (20 ns). E.g. Start position = +100‰ → +2 ns delay

In *Coarse Gate mode* a signal with a period equal to HIT is continuously applied to counters, as explained in Table 7. For more details see the paragraph on *Gated Mode*

Table 7. Short Gating section configuration explained.

Gate1	Enable/Disable the internal coarse gating of counter 1
Gate2	Enable/Disable the internal coarse gating of counter 2
Gate3	Enable/Disable the internal coarse gating of counter 3
Start1, Start2, Start3	Start position of the gate-on window, settable in steps of 10 ns
Stop1, Stop2, Stop3	Stop position of the gate-on window, settable in steps of 10 ns

In the Deadtime subsection it is possible to adjust the hold-off time (in the range 50 ÷ 150 ns) and enable the embedded dead-time correction.

In the Synchronization Output subsection it is possible to enable the generation of voltage pulses on the SYNC OUT output. Two possible synchronization signals are available:

- ✓ *HIT sync*: a 50 ns pulse at the beginning of each Hardware Integration Time
- ✓ *Ref. Clock*: the internal 50 MHz clock is replicated to this output.

Main Window: Plot settings and Playback Control

The plot settings apply only to the images displayed on the screen. No changes are introduced to the data in the memory buffer. Therefore, these parameters do not affect the saved images. All this settings can be changed in real-time during display. The plot settings can be adjusted as explained in Table 8.

After a Snap has been acquired, it is possible to review the images by using the controls shown in Table 9. It is also possible to move along the data using the scrollbar. The current frame number and FLIM step (if in FLIM mode) are also shown.

Table 8. Plot settings and control buttons.

















	Automatically sets the black and white levels of the image according to the present frame: the black level is assigned to the pixel with the minimum number of detected photons in the frame while the white level is assigned to the ones with the maximum count. This setting will remain applied also for the following frames. Since it is possible to have in the following frames pixels with values lower than black or higher than white, they will be respectively indicated in blue or red.
	Resets black and white levels to default values: 0 ÷ 255 for 8-bit images, and 0 ÷ 65535 for 16-bit images.
<i>Flip X</i>	Flip the image along the X-axis.
<i>Flip Y</i>	Flip the image along the Y-axis.
<i>Rotate 90 °CCW</i>	Rotate the image by 90° counter-clockwise. This is default setting of VisualHERMES so that the image is shown in landscape mode.
<i>Enable Time Plot</i>	Enable an additional window that shows a counts vs time plot of up to 6 user selectable pixels.
<i>Keep Windows Docked</i>	If selected, moving the main window will also move together all the other windows.

Table 9. Live viewer control buttons.

	Go to the first acquired frame
	Go to the previous frame
	Go to the next frame
	Go to the last acquired frame
	Play the image sequence backward
	Continuous rewind. When the last (first) acquired frame is displayed, it restarts from the first (last) frame
	Play the image sequence forward

Main Window: Control Buttons

Table 10. Camera control buttons for starting, recording and saving frame acquisitions.

	Start the live-mode acquisition. Once the acquisition has been started, the button becomes a red box. Press it again to stop the acquisition. In FLIM mode the average counts over all FLIM steps is visualized.
	Starts the acquisition of a sequence of frames (Snap mode). If no external trigger is requested, the acquisition starts immediately, and the button becomes a red box. If an external trigger is required, the button turns first in an orange box, then in a red one only when the trigger is detected, and the acquisition really starts. When the box is orange, a click on the button stops the waiting for a trigger. When the box is red, the user must wait for the end of the acquisition.
	Starts the continuous acquisition of frames. If no external trigger is requested, the acquisition starts immediately, and the button becomes a red box. If an external trigger is required, the button turns first in an orange box, then in a red one only when the trigger is detected, and the acquisition really starts. For interrupting the waiting for the external trigger signal or the acquisition, once it has been started, press the button. WARNING: Continuous mode acquisition may generate huge amount of data in short time, depending on acquisition settings. Check "Total saved data" in the <i>Acquisition Parameters Summary box</i> for the actual size of data saved on the HDD.
	Performs the acquisition of a background frame. Once the light is prevented to reach the detector, only dark counts are measured. A dark frame is generated by averaging the <i>number of frames</i> acquired. This frame is then sent to the acquisition electronics to perform hardware background subtraction. The acquisition of the background frame must be performed using the same parameters that will be used for the actual measurement. Any change in the acquisition parameters, including the gate parameters and the dead-time correction settings, REQUIRES a new acquisition of the background frame. The background frame is not stored inside the camera and is lost when the camera is switched off.
	Saves the acquired data by a Snap into a HERMES format file or special HERMES FLIM format.
	Saves the data acquired by a Snap into a multipage TIFF file. The file is compliant with the OME-TIFF specification, which allows embedding in the file metadata all the acquisition parameters for the specific measurement, as well as FLIM mode parameters. OME-TIFF file can be opened with any image reader compatible with TIFF file, since metadata are saved into the Image Description tag in XML format. In order to decode OME-TIFF metadata, it is possible to use free OME-TIFF reader, such as OMERO or the Bio-Formats plugin for ImageJ. For more details see the OME-TIFF web site: http://www.openmicroscopy.org/site/support/ome-model/ome-tiff/ . OME-TIFF metadata for FLIM mode acquisition include the <i>ModuloAlongT</i> tag, which allows the processing of FLIM data with dedicated FLIM software such as FLIMfit (see http://www.openmicroscopy.org/site/products/partner/flimfit).
	Exits HermesView

Main Window: Acquisition Parameters Summary

In this section, the information on the acquisition, based on the actual parameters, is reported. The explanation of all the shown parameters is reported in Table 11.

Table 11. Explanation of the parameters shown in the *Acquisition Parameters Summary* panel.

<i>Frame rate</i>	This is the actual frame rate of a <i>Snap</i> or <i>Continuous Acquisition</i>
<i>Total Frame Time</i>	This is the actual frame exposure time (i.e. the real <i>Hardware Integration Time</i> , multiplied by the number of internal sums)
<i>Total acquisition time</i>	This is the total time required to conclude the <i>Snap</i> acquisition of N_{frames}
<i>Interframe dead-time</i>	This is the actual inter-frame dead-time. Normally it is 40 ns long, but may increase in <i>Advanced</i> mode if very short <i>Hardware Integration Times</i> are selected.
<i>Bit per pixel</i>	Number of bit per pixel (8 or 16)
<i>Snap file size</i>	File dimension for a <i>Snap</i> acquisition with the current parameters
<i>Total saved data (only visible during Continuous Acquisition)</i>	This is the actual size of data so far saved to the disk. The number is updated in real-time after every write operation.

Counter Window

HermsView will show up to three windows (see Figure 18) showing the map of the accumulated counts in each counter. Window for Counter 1 is always visible, windows for Counter 2 and 3 will pop-up if selected in the *Exposure Parameters subsection* of the *Control Panel*. In addition to settings shown in Table 8, it is possible to manually adjust the black and white levels of the image and its contrast by using the controls on the color-bar at the left of the image. After a Live or Snap mode acquisition is stopped, it is possible to directly read the number of photons detected by each pixel by simply moving the mouse pointer over the image (available only if window size is set to default value. Check “Keep windows docked” to revert to default size). In FLIM mode only Counter 1 window is available. In Live mode the average counts over all FLIM steps are visualized, whereas in Snap mode counts for each individual FLIM step are shown. For the sake of clarity let’s consider a Snap of 10 FLIM acquisitions (camera in FLIM mode) and let’s suppose that each acquisition is composed by 50 steps (Gate Shifts, i.e. ‘Gate positions’): a total of 500 frames will be thus shown in Counter 1 window, following a “FLIM first, time second scheme”. With such scheme, the frame sequence would follow this ordering: 1st gate shift of 1st FLIM measurement, 2nd gate shift of 1st FLIM measurement, ..., nth gate shift of 1st FLIM measurement, 1st gate shift of 2nd FLIM measurement, 2nd gate shift of 2nd FLIM measurement, ..., nth gate shift of 2nd FLIM measurement, etc.

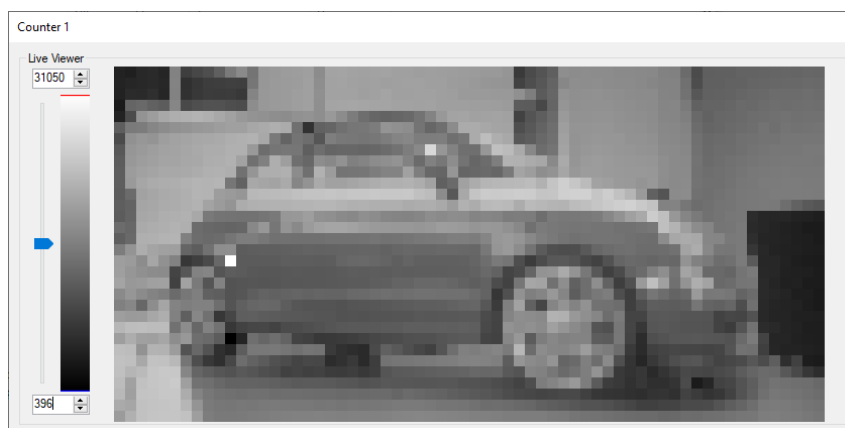


Figure 18. Screenshot of the Counter window.

FLIM Window

When FLIM mode is enabled, an additional FLIM window pops-up, as shown in Figure 19. This graph represents the counted photons in each step (Gate Shift) of the current FLIM acquisition for a selected pixel, and it is thus the TCSPC histogram that reconstructs the waveform under investigation convoluted with the IRF of the system. The IRF is roughly a rectangular shape with a width equal to the Gate width. Up to 6 pixels can be selected to plot. To enable a plot, check one of the coloured checkboxes in the upper left part of the window, then choose which pixel is visualized simply clicking on the desired pixel in Counter 1 window. When more than one plot is enabled, use the ratio buttons below the coloured checkboxes to choose which plot must be updated when clicking on the Counter1 window to change the pixel. A small, coloured box highlights the selected pixel in Counter1 window. The graph is updated in real time in Live mode. In Snap mode it shows the entire FLIM waveform corresponding to the currently visualized FLIM acquisition (i.e. it will not change if, in Counter 1, a different FLIM step from the same FLIM acquisition is visualized). It is possible to choose between linear and logarithmic scale for the Y axis. The *Accumulate* checkbox, if selected, will cause the histogram to accumulate counts among frames. The *Reset* button will clear the entire graph.

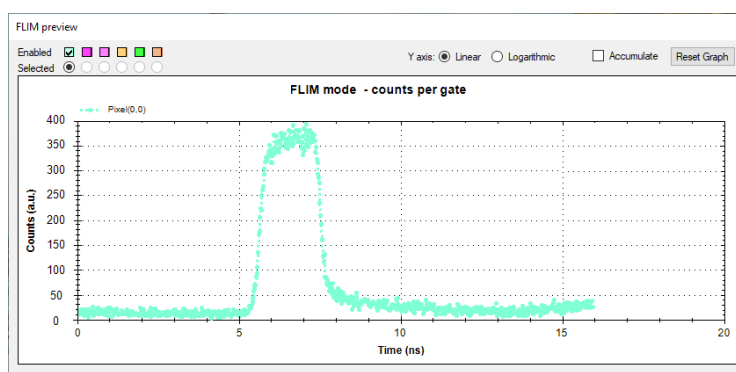


Figure 19. Screenshot of the FLIM window. In this case, the acquisition is the IRF of the system when Gate width is set to 2 ns, and 800 gate steps spanning 16ns are acquired.

Time Plot Window

When *Enable Time Plot* is checked in the *Plot Settings* section, an additional *Time Plot* window pops-up, as shown in Figure 20. Traces in this window represent the photons counted in chosen pixels, frame by frame. Counts from up to 6 pixels can be visualised at the same time. To enable a plot, check one of the coloured checkboxes in the upper left part of the window. To associate a specific pixel to a colour, first select the correspondent radio button, then click the desired pixel in one of the Counter windows. A small, coloured box will highlight the selected pixel. The traces are updated in real time in Live mode. In Snap mode they show the entire snap acquisition. It is possible to choose between linear and logarithmic scale for the Y axis, and to limit the time range to a certain number of frames. The *Reset* button will cancel all traces.



Figure 20. Screenshot of the Time plot window.

HERMES-SDK, File Formats and ImageJ Plugin

HERMES is provided with a Software Development Kit (SDK), composed by a shared library and few example projects. The SDK allows the user acquire data from HERMES and to change operating parameter directly from their own application. It is available for Windows, Mac OS X and Linux operating systems, both in 32- and 64-bit versions. More information on available functions can be found in the related documentation included in the USB key.

Acquired data from Snap acquisitions can be saved both in OME-TIFF format and in a MPD proprietary binary file format. Data from Continuous acquisition can only be saved in MPD proprietary format.

OME-TIFF file could be opened with any image reader compatible with TIFF file, since metadata are saved into the Image Description tag in XML format. In order to decode OME-TIFF metadata, it is possible to use free OME-TIFF readers, such as OMERO or the Bio-Formats plugin for ImageJ. For more details see the OME-TIFF web site: <http://www.openmicroscopy.org/site/support/ome-model/ome-tiff/>. If subarray acquisition is enabled and the number of pixels is not an integer multiple of 32, the TIFF files will have as much rows of 32 pixels are needed to accommodate all pixels, and the missing pixels will be put to 0, e.g. if 67 pixels are acquired, the TIFF image will be 32x3, with the last 29 pixels of the 3rd row set to 0. This ensure that any TIFF compatible software can open the file reporting the correct number of frames and retaining the correct shape of the image.

Proprietary format files produced by HERMES camera are based on the same binary structure, but different file extensions are used for differentiating among data. Photon counting acquisitions are stored in *.hrm* files whereas FLIM mode acquisitions are saved in *.hrmf* files. In addition, each camera is provided with an *.hrme* file containing measured photon detection efficiency. All these files contain binary data, composed by a header with acquisition metadata followed by raw image data which contain the 8/16 bit pixel values in row-major order. The byte order is little-endian for the 16 bit data. Raw data have the following meaning:

.hrm files: data represents photon counts in each pixel during each Exposure Time, with acquisition parameters reported in the header. In case more counters are used, data are interlaced, i.e., the sequence of frames is the following: 1st frame of 1st counter, 1st frame of 2nd counter, 1st frame of 3rd counter, 2nd frame of 1st counter, etc. If a Subarray is acquired, differently from TIFF format only the effective pixels will be saved, to reduce the file size and ease the postprocessing. The number of pixels is reported in the header. However, to help in reconstructing the “shape” of the image, also the number of column and rows are reported in the header, again rounding up the number of rows to accommodate all the pixels. This means that $Nrows * Ncolumns > Npixels$ if a subarray is acquired and $Npixels$ is not a multiple of 32.

.hrmf files: data represents photon counts in each pixel during each Exposure Time, with acquisition parameters reported in the header. Images follow a "FLIM first, time second scheme", 1st gate shift of 1st FLIM measurement, 2nd gate shift of 1st FLIM measurement, ..., nth gate shift of 1st FLIM measurement, 1st gate shift of 2nd FLIM measurement, 2nd gate shift of 2nd FLIM measurement, ..., nth gate shift of 2nd FLIM measurement, etc.

.htme files: data represent measured Photon Detection Efficiency for each pixel. Values range from 0 to 10000, i.e. a 32.5% PDE will be expressed as 3250. Each frame represents a wavelength, whose range and step are reported in the header.

The header is composed by a signature of 8 bytes (0x4d5044ff04000000, with byte 0 set to 4d), and a metadata section of 1024 bytes, as reported in Table 12. Note that multibyte numerical fields are little-endian.

Table 12. Header structure of HERMES proprietary file formats .hrm, .hrmf, .hrme.

Byte offset	Number of bytes	Description
0	10	Unique camera ID (string)
10	32	HERMES serial number (string)
42	2	Firmware version (1.11 saved as 111)
44	1	Firmware custom version (standard = 0)
45	20	Acquisition data&time (string)
65	35	Unused
100	1	Number of rows
101	1	Number of columns
102	1	Bit per pixel
103	1	Counters in use
104	2	Hardware integration time (multiples of 10ns)
106	2	Summed frames
108	1	Dead time correction enabled
109	1	Internal gate duty-cycle (0-100%)
110	2	Holdoff time (ns)
112	1	Background subtraction enabled
113	1	Data for counters 1 and 2 are signed
114	4	Number of frames in the file
118	1	Image is averaged
119	1	Counter which is averaged
120	2	Number of averaged images
122	1	Internal gate duty-cycle for counter2 (0-100%)

123	1	Internal gate duty-cycle for counter3 (0-100%)
124	2	Frames per sync-in pulse
126	2	Number of pixels
128	72	Unused
200	1	FLIM enabled
201	2	FLIM shift %
203	2	FLIM steps
205	4	FLIM frame length (multiples of 10ns)
209	2	FLIM bin width (fs)
211	9	Unused
220	1	Multi gate mode: 2 = dual, 3 = triple
221	2	Multi gate mode: start position (-500 - +500)
223	1	Multi gate mode: first gate width (0-100%)
224	1	Multi gate mode: second gate width (0-100%)
225	1	Multi gate mode: third gate width (0-100%)
226	2	Multi gate mode: gap1 (0-800)
228	2	Multi gate mode: gap2 (0-800)
230	2	Multi gate mode: calibrated binwidth in fs
232	1	Coarse gate 1 enabled
233	2	Coarse gate 1 start pos. (multiples of 10ns)
235	2	Coarse gate 1 stop pos. (multiples of 10ns)
237	1	Coarse gate 2 enabled
238	2	Coarse gate 2 start pos. (multiples of 10ns)
240	2	Coarse gate 2 stop pos. (multiples of 10ns)
242	1	Coarse gate 3 enabled
243	2	Coarse gate 3 start pos. (multiples of 10ns)
245	2	Coarse gate 3 stop pos. (multiples of 10ns)
247	53	Unused
300	1	PDE measurement
301	2	Start wavelength (nm)
303	2	Stop wavelength (nm)
305	2	Step (nm)
307	717	Unused

In order to easily visualize and elaborate data stored in the proprietary *.hrm*, *.hrmf* and *.hrme* file formats, a plugin for ImageJ software (<http://rsb.info.nih.gov/ij/>) is also provided. The plugin is compatible both with ImageJ (tested on v. 1.49q) and with Fiji (<http://fiji.sc/Fiji>), which is essentially a distribution of ImageJ together with several useful plugins.

In order to install the plugin follow this procedure:

- for *ImageJ* (tested on v. 1.49q), launch ImageJ and select the menu item *Plugins → Install...*, then follow the instructions and select the file *HERMES_Reader.jar* provided in HERMES USB key. The "*Save Plugin, Macro or Script...*" dialog appears with a list of your currently installed ImageJ plugins. Select a folder, such as the Input-Output folder, and save the *HERMES_Reader.java* file there. Do not change the name *HERMES_Reader.jar*, as it follows ImageJ naming conventions, and it is not seen by ImageJ if it does not contain an underscore.
- for *Fiji*, launch Fiji and select the menu item *Plugins → Install Plugin...*, then follow the instructions and select the file *HERMES_Reader.jar* provided in HERMES USB key. Restart Fiji.

In order to use the plugin, select *HERMES_Reader* under the *Plugins* menu. It will be in the location you've previously chosen for ImageJ, or at the end of the menu for Fiji. An "*Open HERMES file...*" dialog appears. Select the *.hrm*, *.hrmf* or *.hrme* file you wish to load. ImageJ will now ask you how to deal with signed data.

If data is 8bit, there are three options:

- Convert data to 32bit float
- Import unsigned data as is and convert signed data to 32bit float
- Import all data as is (this means ImageJ will interpret signed data as unsigned, e.g. the number -1, which in 8 bit binary is 11111111, will be shown as 255)

If data is 16bit, there are four options:

- Convert data to 32bit float
- Import unsigned data as is and convert signed data to 32bit float
- Import all data as is (this means ImageJ will interpret signed data as unsigned, e.g. the number -1, which in binary is 11111111, will be shown as 255)
- Import all data as is and use an ImageJ calibration function to map signed data (this means ImageJ will remap data to show signed values, e.g. the number -1, which in 16 bit binary is 1111111111111111 and will read as 65535 without remapping, will be properly shown as -1).

If the selected file is properly formatted and no error occurred, an image window for each HERMES counter enabled opens. Frames can be skimmed using the controller at the bottom of each window. Selecting from the menu the command *Image→Show Info...* will show all camera parameters for the acquisition. If subarray acquisition is enabled and the number of pixels is not an integer multiple of 32, the displayed stack will have as much rows of 32 pixels needed to accommodate all pixels, and the missing pixels will be put to 0, e.g. if 67 pixels are acquired, the image stack will be 32x3, with the last 29 pixels of the 3rd row set to 0. This ensure that ImageJ reports the correct number of frames, and the shape of the image is retained.

HERMES Specifications

Specifications @ T = 30 °C

	Min	Typ	Max	Units
SPAD Photon Detection Efficiency (PDE)¹ Average on entire array @ 350 nm @ 450 nm @ 650 nm @ 850 nm	19 33 14 3	24 42 18 4		%
SPAD Dark-counting rate (DCR) Percentage of SPAD pixels with DCR < 100 c/s Percentage of SPAD pixels with DCR < 1000 c/s		90 95		%
SPAD Afterpulsing probability (at minimum SPAD dead-time)		1		%
SPAD Adjustable dead-time (more than 60 user selectable and calibrated values)	Minimum	50		ns
	Maximum	125		ns
SPAD active area diameter		30		µm
SPAD pitch		150		µm
SPAD pixels		2048		
Imager Fill Factor (without a Micro Lens Array)		3.14		%
Optical crosstalk			0.01	%
Micro Lens Array (MLA) Characteristics (optional) micro-lens type micro-lens diameter micro-lens pitch		round		
		150		µm
		150		µm
Imager Fill Factor (with MLA, incoming beam aperture < 9°, full angle)		75		%
Imager PDE¹ (with MLA, incoming beam aperture < 9°, full angle) Average on entire array @ 350 nm @ 400 nm @ 640 nm @ 840 nm	14 25 10 2	18 31 13 3		%
Defective pixels per array - DCR (i.e., with DCR > 600 kc/s)		0	5	
Defective pixels per array - PDE (i.e., with SPAD-PDE or IMAGER-PDE lower than 50% of the minimum value)		0	5	
Frame rate			96	kframe/s
Interframe dead-time		40		ns
Time-Gated FLIM mode (see user manual) Gate Width Gate Steps Step Size Measurement Time range Laser Sync Out	1.5		20	ns
		1000		
		20		ps
		20		ns
		50		MHz

Photon Counting Dynamics	@ 96 @ 6 @ 0.375	kframe/s kframe/s kframe/s			8 12 16	bit
Higher frame rates are possible by reducing the number of acquired pixels						
Operating Conditions (Ambient Temperature)	15			40	°C	
Electrical Characteristics Supply Voltage USB connector Coaxial Inputs SYNC OUT output	+12 Vdc USB-C 3.3 V CMOS; 5 V-tolerant 3.3 V CMOS; drives 50 Ω					
Optical Interface	Thorlabs® SM1 and 30 mm cage systems. C-mount with adapter					
Dimensions (without C-mount adapter and cables)	69.5 mm (H) x 97.1 mm (W) x 42.93 mm (D)					
Weight (camera; ring; coax)	365 g; 16 g; 140 g					

¹ SPAD-PDE is the PDE of the active area of a SPAD sensor; ImagerPDE is the PDE of a square pixel which includes a SPAD sensor and whose side is equal to the imager pitch. Camera SPADs are fabricated using a CMOS process. Therefore, depending on actual production run, they may exhibit PDE curves with more or less pronounced ringing and variable peaks and valleys exact position. Indicated PDE values may thus correspond to slightly different wavelengths respect to those stated above.

System requirements

- High-speed USB-C interface.
- Host computer (minimum requirements)
 - 2 GHz processor and 2 GB of RAM
 - SSD recommended for full speed continuous acquisition.
- Supported operating systems
 - HermesView
 - Microsoft Windows 10,11 (32- or 64-bit) versions
 - SDK and ImageJ Plugin
 - Microsoft Windows 10,11 (32- or 64-bit) versions
 - Linux Ubuntu 20.04 LTS 64 bit, or compatible distributions (different distributions should work but were not tested).
- Tested ImageJ versions (different versions should work, but were not tested)
 - Standalone ImageJ: version 1.49q
 - Fiji distribution: version 2.0.0-rc-28/1.50b

Appendix I: Description of Hermes characterization files

Hermes cameras are fully characterized before shipping by MPD. Some of the characterization files are shared with customers and included in the provided USB key. This document describes how to read and understand them.

Dark counting rate cumulative distribution - BG_CumDistribGraph.tif

This file shows the cumulative distribution of the dark counts over all the pixels of the imager. The distribution is obtained ordering in ascending order the dark counting rate of all the pixels and normalizing the x axis to 100%. It must be read as follows: given a desired maximum dark counting rate, represented on the y axis, the percentage of pixels below that value is given by the corresponding x value.

Dark counting rate map – DCR 50ns averaged.hrm

This file shows a map of the dark counting rate over all the pixels of the imager when measured with a dead-time of 50 ns and averaging the acquired data over 100 frames 104 ms long. The DCR is thus shown in counts per frame (of 104 ms). The file can be opened using ImageJ with the provided Hermes plugin.

Detection efficiency map and average

Given the very good reproducibility and consistency of the Hermes photon detection efficiency (PDE) among fabricated samples, Micro Photon Devices Srl is not measuring it on all fabricated devices, but only on randomly selected samples. To check if this data is available and to request it, customers can write to support@micro-photon-devices.com. Such data, if available, will be sent to customers.

In case of the Hermes without the micro lens array, the SPAD-PDE will be provided through 2 files:

1. Hermes_SNxx_PDE_50nm_efficiency.hrme. This file contains the map of the detection efficiency over all the SPAD sensors of the array. xx refers to the serial number of the module.
2. Hermes_SNxx_PDE.xlsx. This file contains the Hermes detection efficiency averaged over all the diodes of the array as a function of the wavelength. Xx refers to the serial number of the module.

In case of the Hermes with the micro lens array, the ImagerPDE will be provided through 3 files:

The files will be named ImagerPDE_SNxx-F#yyy.hrme, where SNxx is the serial number of the camera and F#xx is the Fnumber of the light impinging the detector. Since the SPAD active area PDE depends on the wavelength and the microlens CE depends on the wavelength AND on the incoming beam F-number, we decided to provide the ImagerPDE per pixel and as a function of wavelength at different impinging light beam F-Numbers. Since we internally measure the ImagerPDE at 3 F-numbers only, 3 files are provided.

Finally, .hrme files are movie-files composed by 61 frames, each corresponding to a different wavelength, starting from 400 nm and ending at 1000 nm in 10 nm steps. For each pixel, the value reported corresponds

to the measured PDE percentage multiplied by 100, i.e., a value of 3856 corresponds to a PDE of 38.56%. The file can be opened using ImageJ with the provided Hermes plugin or with any other software after having read the file specifications in the user manual.

Note on ImageJ processing

We found out that some ImageJ processing plugins, in particular Stack 3D Surface Plot, may contain some bugs, depending on your ImageJ version. Imported data from Hermes files are correct as far as no processing is applied. Please be careful when applying any processing, since other bugs may be present. For further details, contact MPD at info@micro-photon-devices.com

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